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# APPLICATIONS OF DIFFERENTIAL ALGEBRA FOR COMPUTING LIE ALGEBRAS OF INFINITESIMAL CR-AUTOMORPHISMS 

MASOUD SABZEVARI, AMIR HASHEMI, BENYAMIN M.-ALIZADEH, AND JOËL MERKER


#### Abstract

We perform detailed computations of Lie algebras of infinitesimal CR-automorphisms associated to three specific model real analytic CR-generic submanifolds in $\mathbb{C}^{9}$ by employing differential algebra computer tools - mostly within the MAPLE package DifferentialAlgebra - in order to automate the handling of the arising highly complex linear systems of PDE's. Before treating these new examples which prolong previous works of Beloshapka, of Shananina and of Mamai, we provide general formulas for the explicitation of the concerned PDE systems that are valid in arbitrary codimension $k \geqslant 1$ and in any CR dimension $n \geqslant 1$. Also, we show how Ritt's reduction algorithm can be adapted to the case under interest, where the concerned PDE systems admit so-called complex conjugations.


## 1. Introduction

The Lie algebras $\mathfrak{a u t}_{C R}\left(M_{\text {model }}\right)$ of infinitesimal CR-automorphisms of various model - in the sense of Beloshapka - Cauchy-Riemann (CR) generic submanifolds $M_{\text {model }} \subset \mathbb{C}^{n+k}$ of codimension $k \geqslant 1$ and of CR dimension $n \geqslant 1$ are key algebraic features which open the door to a potentially infinite number of new Cartan geometries. Indeed, the knowledge of $\mathfrak{a u t}_{C R}\left(M_{\text {model }}\right)$ and of its isotropy subalgebras $\mathfrak{a u t}_{C R}\left(M_{\text {model }}, p\right)$ at points $p \in M_{\text {model }}$ strongly intervenes when one endeavours to build Cartan connections associated to all geometry-preserving real analytic deformations $M \subset \mathbb{C}^{n+k}$ of a chosen model. It is well known that procedures due to Cartan and to Tanaka exist to perform such constructions (see $[11,6,13,1,19,26,25]$ in a CR context), although the practical outcome appears most of the times to be delicate and unpredictable.

In addition, there has recently been an increasing interest towards complete classification of CR-generic submanifolds according to their algebras of infinitesimal CR-automorphisms. Notably, Beloshapka and Kossovskiy [7] classified homogeneous CR-generic submanifolds $M^{4} \subset \mathbb{C}^{3}$ of CR dimension 1 , while a bit before, Fels and Kaup [14] classified the Levi-degenerate homogeneous 2-nondegenerate hypersurfaces $M^{5} \subset \mathbb{C}^{3}$ of dimension five.

Far beyond for what concerns the appearing (co)dimensions, Beloshapka and his school in the last decade devised general procedures to cook up model CR-generic submanifolds that, most often, have rigid polynomial defining equations. But when some concrete equation of a CR-generic manifold is given, one unpleasant obstacle happens to be the complexity and the length of the computations that are required

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to attain the full Lie algebras of infinitesimal CR-automorphisms (see [1, 5, 25, 26, 30]), an obstacle which motivates the present work.

By $n \geqslant 1$ and $k \geqslant 1$ throughout this paper, we shall mean the CR dimension and the codimension of a real analytic local CR-generic submanifold $M^{2 n+k} \subset \mathbb{C}^{n+k}$ passing through a reference point, say through the origin. Beloshapka in [4], introduced a significant class of CR-generic manifolds with several nice properties (see $e . g$. Theorem 14 in [4]), that he denoted by $Q(n, k) \subset \mathbb{C}^{n+k}$ and called universal models. He also computed the algebras of infinitesimal CR-automorphisms associated to the simplest model $Q(1,2)$ in [5], and he derived some interesting stability results. Subsequently, Shananina computed such algebras for the universal models $Q(1, k)$ with $3 \leqslant k \leqslant 7$ in [30] and derived expected consequences too (see Theorem 1, Propositions 1 and 2 and Corollary 1 of [30]). Finally, in [21], Mamai studied Lie algebras of infinitesimal CR-automorphisms associated to some universal models $Q(1, k)$ for $8 \leqslant k \leqslant 12$, though without presenting details. As far as the authors are aware of, in CR dimension $n=1$, no higher codimensions have been explored. Understandably, as much as the dimension or codimension of a CRgeneric submanifold $M^{2 n+k} \subset \mathbb{C}^{n+k}$ increases, the size and the complexity of the corresponding computations of $\mathfrak{a u t} t_{C R}(M)$ growths rapidly, hence an automation would be welcome, even a partial one.

Serendipitously, an important, recently renewed, much related subject has been extensively studied: Differential (Computer) Algebra, cf. [9, 10, 15, 20, 28]. There, one employs algebraic tools - like the ones of Gröbner bases theory - in order to solve systems of partial differential equations, or in order to find the Lie symmetries of differential equations, a vast area too. Over the past few years, several relative packages have been developed within various computer algebra systems. For instance, two Maple packages were designed in this direction, firstly DifferentialAlgebra by Boulier, Lazard, Ollivier, Petitot ([9]), and secondly diffgrob2 by Mansfield ([22]).

In this paper, we aim to provide an effective algorithm in order to compute the Lie algebras $\mathfrak{a u t}_{C R}\left(M_{\text {model }}\right)$ associated to model real analytic CR-generic submanifolds $M_{\text {model }}^{2 n+k} \subset \mathbb{C}^{n+k}$, by the valuable means of differential algebra, supplemented by some new operations. For this purpose, we shall denote by LinCons the PDE systems that have constant (complex) coefficients, precisely as the ones we shall encounter several times. Since these systems admit complex-valued equations, we equip at first the fundamental Ritt's reduction theorem with an operator, which we call the bar-reduction, and we extend it to gain the following conclusion, more appropriate to treat the arising complex-valued LinCons PDE systems (see Theorem 3.2):

Theorem 1.1. (EXtENDED Ritt's REDUCTION THEOREM) Consider a differential polynomial ring $R=\mathbb{C}\left\{u_{1}, \ldots, u_{n}\right\}$ over the field of complex numbers, let $\Theta$ be the set of its derivation operators, and let ' $>$ ' be a ranking over $\Theta U$. Furthermore, assume that $p \in R$ is a LinCons differential polynomial and let $Q$ be a finite set of LinCons differential polynomials. Then, there exists $r \in R$, and for each $q \in Q$, there exists $\theta_{q}, \theta_{\bar{q}} \in \Theta$ and $c_{q}, c_{\bar{q}} \in K$ satisfying the following conditions:

- $p=\left(\sum_{q \in Q} c_{q} \theta_{q} q\right)+\left(\sum_{q \in Q} c_{\bar{q}} \theta_{\bar{q}} \bar{q}\right)+r$,
- for each $q$ appearing in this summation we have:

$$
\operatorname{rank}(r)<\min _{>}\left\{\operatorname{rank}\left(\theta_{q} q\right), \operatorname{rank}\left(\theta_{\bar{q}} \bar{q}\right)\right\}
$$

- no term of $r$ is a derivation of either $\operatorname{rank}(q)$ or $\operatorname{rank}(\bar{q})$ for each $q \in Q$.

Using this result, we modify the Rosenfeld-Gröbner algorithm to an algorithm we call the $L R G$ algorithm (Algorithm 3 below) in such a way that it works appropriately in the case of our LinCons complex-valued PDE systems. It is noteworthy that, for the sake of simplicity, we study only rigid CR-generic submanifolds $M^{10} \subset \mathbb{C}^{1+8}$ (see Subsection 4.4 for more details), because the arising PDE systems are LinCons; of course, a more general algorithm could be described for non-rigid $M_{\text {model }}^{2 n+k} \subset \mathbb{C}^{n+k}$, the PDE system still being linear, though with nonnecessarily constant coefficients.

Specifically, we employ our LRG algorithm for computing explicitly the Lie algebras of infinitesimal CR-automorphisms associated to the following three real analytic rigid CR-generic submanifolds $M^{10} \subset \mathbb{C}^{9}$, represented in coordinates $(z, w)=\left(z, w^{1}, \ldots, w^{8}\right)$ as the graphs of the following shared six defining equations:

$$
\begin{array}{ll}
w^{1}-\bar{w}^{1}=2 i z \bar{z}, & w^{2}-\bar{w}^{2}=2 i\left(z^{2} \bar{z}+z \bar{z}^{2}\right), \\
w^{3}-\bar{w}^{3}=2\left(z^{2} \bar{z}-z \bar{z}^{2}\right), & w^{4}-\bar{w}^{4}=2 i\left(z^{3} \bar{z}+z \bar{z}^{3}\right), \\
w^{5}-\bar{w}^{5}=2\left(z^{3} \bar{z}-z \bar{z}^{3}\right), & w^{6}-\bar{w}^{6}=2 i z^{2} \bar{z}^{2}, \tag{1}
\end{array}
$$

together with:

$$
\begin{aligned}
& \text { First model } \mathbb{M}^{1}:\left\{\begin{array}{l}
w^{7}-\bar{w}^{7}=2 i\left(z^{4} \bar{z}+z \bar{z}^{4}\right), \\
w^{8}-\bar{w}^{8}=2\left(z^{4} \bar{z}-z \bar{z}^{4}\right),
\end{array}\right. \\
& \text { Second model } \mathbb{M}^{2}:\left\{\begin{array}{l}
w^{7}-\bar{w}^{7}=2 i\left(z^{3} \bar{z}^{2}+z^{2} \bar{z}^{3}\right), \\
w^{8}-\bar{w}^{8}=2\left(z^{3} \bar{z}^{2}-z^{2} \bar{z}^{3}\right),
\end{array}\right. \\
& \text { Third model } \mathbb{M}^{3}:\left\{\begin{array}{l}
w^{7}-\bar{w}^{7}=2 i\left(z^{3} \bar{z}^{2}+z^{2} \bar{z}^{3}\right), \\
w^{8}-\bar{w}^{8}=2 i\left(z^{4} \bar{z}+z \bar{z}^{4}\right) .
\end{array}\right.
\end{aligned}
$$

For this, we use the MAPLE package DifferentialAlgebra to carry out the necessary computations. Nevertheless, these computations involve complex integers and functions and hence it is not possible to perform directly this package in this respect. That is why, we need also to utilize a new reduction called barreduction that uses complex conjugation to obtain a full remainder (see Section 3). Executing long computations, we achieve the following results. Of course, the main interest of our algorithmic partly automatize approach is to open the door to a wealth of other examples taking inspiration from Beloshapka's universal models.

Theorem 1.2. The Lie algebras of infinitesimal $C R$-automorphisms $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{1}\right)$, $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{2}\right)$ and $\mathfrak{a u t} t_{C R}\left(\mathbb{M}^{1}\right)$ of the three real analytic generic CR-generic submanifolds $\mathbb{M}^{1}, \mathbb{M}^{2}$ and $\mathbb{M}^{3}$ of $\mathbb{C}^{1+8}$ are of dimensions 12,12 and 11 , respectively and are generated by the $\mathbb{R}$-linearly independent real parts of the following collections
of holomorphic vector fields:
$\left(\mathbb{M}^{1}\right)$

$$
\left\{\begin{aligned}
\mathrm{X}_{i} & :=\partial_{w_{i}}, \quad i=1, \ldots, 8 \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}} \\
\mathrm{X}_{10} & :=i z \partial_{z}-w^{3} \partial_{w^{2}}+w^{2} \partial_{w^{3}}-2 w^{5} \partial_{w^{4}}+2 w^{4} \partial_{w^{5}}-3 w^{8} \partial_{w^{7}}+3 w^{7} \partial_{w^{8}} \\
\mathrm{X}_{11} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(4 w^{4}+2 i z^{4}\right) \partial_{w^{7}}+\left(4 w^{5}+2 z^{4}\right) \partial_{w^{8}} \\
\mathrm{X}_{12} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}+-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+\left(-4 w^{5}+2 z^{4}\right) \partial_{w^{7}}+\left(4 w^{4}-2 i z^{4}\right) \partial_{w^{8}}
\end{aligned}\right.
$$

$$
\left\{\begin{aligned}
\mathrm{X}_{i} & :=\partial_{w_{i}}, \quad i=1, \ldots, 8 \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}}, \\
\mathrm{X}_{10} & :=i z \partial_{z}-w^{3} \partial_{w^{2}}+w^{2} \partial_{w^{3}}-2 w^{5} \partial_{w^{4}}+2 w^{4} \partial_{w^{5}}-w^{8} \partial_{w^{7}}+w^{7} \partial_{w^{8}} \\
\mathrm{X}_{11} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(2 w^{4}+6 w^{6}\right) \partial_{w^{7}}+2 w^{5} \partial_{w^{8}} \\
\mathrm{X}_{12} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+2 w^{5} \partial_{w^{7}}+\left(-2 w^{4}+6 w^{6}\right) \partial_{w^{8}} ;
\end{aligned}\right.
$$

$$
\left\{\begin{aligned}
\mathrm{X}_{i} & :=\partial_{w_{i}}, \quad i=1, \ldots, 8 \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}}, \\
\mathrm{X}_{10} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(2 w^{4}+6 w^{6}\right) \partial_{w^{7}}+\left(4 w^{4}+2 i z^{4}\right) \partial_{w^{8}} \\
\mathrm{X}_{11} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+2 w^{5} \partial_{w^{7}}+\left(-4 w^{5}+2 z^{4}\right) \partial_{w^{8}}
\end{aligned}\right.
$$

The paper is organized as follows. Section 2 contains an overview of the necessary background concerning the theory of differential algebras. In Section 3, we present the extended Ritt's reduction algorithm and we show how to utilize the differential algebraic tools to resolve a system of partial differential equations. In Section 4, we present a general method/strategy to compute the Lie algebra of infinitesimal CR-automorphisms of arbitrary generic real analytic CR-generic submanifolds $M \subset \mathbb{C}^{n+k}$. Section 5 is devoted to compute in detail the Lie algebra of infinitesimal CR-automorphisms $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{1}\right)$, associated to the first model $\mathbb{M}^{1}$. However, we do not present the intermediate computations of $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{2}\right)$ and $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{3}\right)$ since they are similar to those of $\mathbb{M}^{1}$ and offer no new aspect. Tables of Lie brackets appear at the end.

## 2. Differential algebra preliminaries

In this section, we present a brief overview of basic definitions, notation and results in differential algebra. Two extensive surveys of this subject are: [20, 28].

Definition 2.1. An operator $\delta: R \rightarrow R$ over the algebraic ring $R$ is called a derivation operator, if for each $a, b \in R$ we have:

$$
\begin{aligned}
\delta(a+b) & =\delta(a)+\delta(b) \quad \text { and } \\
\delta(a b) & =\delta(a) b+a \delta(b)
\end{aligned}
$$

A differential ring is a pair $(R, \Delta)$ where $R$ is a ring equipped with a collection $\Delta=\left\{\delta_{1}, \ldots, \delta_{m}\right\}$ of commuting derivations operators over it, satisfying:

$$
\delta_{i} \delta_{j} a=\delta_{j} \delta_{i} a, \quad(i, j=1 \ldots m ; a \in R)
$$

For simplicity, we suppress the dependence on $\Delta$ in the notation and denote a differential ring just by $R$. If $m=1$, then $R$ is called an ordinary differential ring; otherwise it will be called partially. An algebraic ideal $I$ of $R$ is called a differential ideal when it is closed under the action of derivations of $R$, namely $\delta a \in I$ for each $\delta \in \Delta$ and $a \in I$.

Example 2.2. The ring of polynomials $\mathbb{C}\left[x_{1}, \ldots, x_{m}\right]$ over the variables $x_{1}, \ldots, x_{m}$ with rational coefficients together with the set of operators $\partial / \partial x_{1}, \ldots, \partial / \partial x_{m}$ is a differential ring.

Let $R$ be a differential ring with $\Delta=\left\{\delta_{1}, \ldots, \delta_{m}\right\}$. Here, we introduce a collection of notations in differential algebra via the following itemized list:

- We denote by $\Theta$ the free multiplicative commutative semigroup generated by the elements of $\Delta$, namely

$$
\Theta:=\left\{\delta_{1}^{t_{1}} \delta_{2}^{t_{2}} \ldots \delta_{m}^{t_{m}} \quad t_{1}, \ldots, t_{m} \in \mathbb{N}\right\}
$$

Each element $\theta=\delta_{1}^{\alpha_{1}} \cdots \delta_{m}^{\alpha_{m}}$ of $\Theta$ is called a derivation operator of $R$ and furthermore the sum $\operatorname{ord}(\theta):=\sum_{i=1}^{m} t_{i}$ is called the order of $\theta$. Then $\theta a$ is said to be a derivative of $a \in R$ of order ord $(\theta)$.

- For an arbitrary subset $S$ of $R$, set $\Theta S:=\{\theta s \mid s \in S, \theta \in \Theta\}$. It is the smallest subset of $R$ containing $S$ which is stable under derivation.
- An algebraic ideal of $R$ is called a differential ideal, if it is closed under the derivation operators. We denote by $(S)$ and $[S]$ respectively, the smallest algebraic and differential ideals of $R$ containing $S$. In fact, $[S]=(\Theta S)$. This fact provides an algebraic approach to differential ideals which enables one to employ algebraic means.
- For a field of characteristic zero $K$, a differential polynomial ring:

$$
R:=K\left\{u_{1}, \ldots, u_{n}\right\}:=K[\Theta U]
$$

is the usual commutative polynomial ring generated by $\Theta U$ over $K$, where $U:=\left\{u_{1}, \ldots, u_{n}\right\}$ is the set of differential indeterminate.

- For two certain derivatives $\theta u$ and $\phi u$ of a same differential indeterminate $u$, we denote by $\operatorname{lcd}(\theta u, \phi u)$ the least common derivative between $\theta u$ and $\phi u$, easily seen to be:

$$
\operatorname{lcd}(\theta u, \phi u)=\operatorname{lcm}(\theta, \phi) u
$$

In this paper we let $K$ be a differential field of characteristic zero.

Definition 2.3. Let $R=K\{U\}$ be a differential polynomial ring with the set of indeterminates $U=\left\{u_{1}, \ldots, u_{n}\right\}$. A ranking $>$ is an ordering over $\Theta U$ compatible with the derivation act over $\Theta U$, in the sense that for each derivation $\delta \in \Theta$ and for each $v, w \in \Theta U$ we have:

- $\delta v>v$,
- $v>w \Rightarrow \delta v>\delta w$.

For each $\theta, \phi \in \Theta$ and $v, w \in U$, a ranking $>$ for which the statement $\operatorname{ord}(\theta)>$ $\operatorname{ord}(\phi)$ implies that $\theta v>\phi w$ is called orderly. Simultaneously, if the assumption $v>w$ gives $\theta v>\phi w$, then $>$ is called elimination. Moreover, for a fixed ranking $>$ over $\Theta U$ and for a differential polynomial $p \in R=K\left\{u_{1}, \ldots, u_{n}\right\}$, the leader $\operatorname{ld}(p)$ of $p$ is the highest derivative appearing in $p$ with respect to $>$. If $\operatorname{ld}(p)=u$ and $d$ is the degree of $u$ in the expression of $p$ then, the initial $\operatorname{in}(p) \in K$ is defined to be the coefficient of $u^{d}$ in $p$. Finally, $u^{d}$ is called the rank of $p$, denoted by $\operatorname{rank}(p)$.

## 3. Differential algebra and pde systems

Each differential polynomial ring $R=K\{U\}$ can be considered as the conventional polynomial ring $K[\Theta U]$ whose indeterminates are derivations of $R$. This enables one to use the conventional algebraic tools and get useful information about the differential polynomial ring and its differential ideals. In this section, we employ the Rosenfeld-Gröbner algorithm to discuss a system of partial differential equations, using algebraic operations. For a PDE system $\Sigma \subset R$, the Rosenfeld-Gröbner algorithm presents the radical differential ideal generated by $\Sigma$ as an intersection of a finite number of differential ideals which are called regular differential ideals. Those are some differential ideals $I$ represented by a canonical representative $C$, i.e. a set of differential polynomials which depends only on $I$ and the given ranking. A canonical representative of the differential ideal $I$ helps to solve ideal membership problem, which is a key computational tool to analyze a PDE system. An implementation of the Rosenfeld-Gröbner algorithm is available in the MAPLE package diffalg, and it was recently renovated into the package DifferentialAlgebra.

One of the main contributions of this paper is the use of Rosenfeld-Gröbner algorithm - followed by performing some further algebraic manipulations - for considering our PDE systems. It is worth emphasizing that the PDE systems that we deal with in this paper are linear and admit complex equations. Then, we have to equip the Rosenfeld-Gröbner algorithm with a certain operator which enables to treat with such systems. Moreover, in the considerably significant class of rigid CR-generic submanifolds (see the end of section 4 for definition), the under consideration PDE systems are not only complex and linear but also with constant coefficients and it is therefore reasonable to consider such systems more seriously. For brevity, let us call this type of systems by LinCons systems and also similarly, let us call each linear differential polynomial with constant coefficients LinCons polynomial ${ }^{1}$. Computation with the Rosenfeld-Gröbner algorithm are comparatively less expensive. Furthermore, in this case there is no need longer to decompose the

[^0]differential ideal generated by the system into regular differential ideals (a complicated aspect of the general algorithm).
3.1. Extended Ritt's reduction algorithm. Let us therefore recall the Ritt's reduction algorithm, restricted to LinCons differential polynomials. Therefore, the reduction algorithm described here shall be a weak version of the Ritt's reduction algorithm in comparison with the version of [28, 20]. Let us recall the definition of partial divisibility for differential polynomials.
Definition 3.1. Consider two LinCons differential polynomials $p_{1}$ and $p_{2}$. We say that $p_{2}$ reduces $p_{1}$ due to the Ritt's reduction algorithm, whenever there exists a certain derivation $\theta$ with $\operatorname{rank}\left(p_{1}\right)=\operatorname{rank}\left(\theta p_{2}\right)$. In this case, the result of reduction is:
$$
r:=p_{1}-\frac{\operatorname{in}\left(p_{1}\right)}{\operatorname{in}\left(p_{2}\right)} \theta p_{2}
$$

When $\theta$ is proper, we call $r$, the partial remainder of $p_{1}$ on division by $p_{2}$.
One notices that in this definition, if $\operatorname{rank}\left(p_{1}\right)=\operatorname{rank}\left(p_{2}\right)$ then $\theta$ must be the identity element of $\Theta$ and the Ritt's reduction coincides with the conventional division algorithm for multivariate polynomial rings.

Theorem 3.1. (RITT'S REDUCTION THEOREM) Consider a differential polynomial ring $R=K\left\{u_{1}, \ldots, u_{n}\right\}$ over a field $K$ of characteristic zero, let $\Theta$ be the set of derivation operators and let ' $>$ ' be a ranking over $\Theta U$. Furthermore, assume that $p \in R$ is a LinCons differential polynomial and let $Q$ be a finite set of LinCons differential polynomials. Then, there exists $r \in R$, and for each $q \in Q$, there exists $\theta_{q} \in \Theta$ and $c_{q} \in K$ satisfying the following conditions:

- $p=\left(\sum_{q \in Q} c_{q} \theta_{q} q\right)+r$,
- $\operatorname{rank}(r)<\operatorname{rank}\left(\theta_{q} q\right)$, for each $q$ appearing in the summation,
- no term of $r$ is a derivation of $\operatorname{rank}(q)$ for each $q \in Q$.

Here, the differential polynomial $r \in R$ is called the remainder of $p$ on division by $Q$. In order to prove this Theorem, let us display first the Ritt's reduction algorithm ensuing its assertion. Then, the correctness and termination of this algorithm proves Theorem 3.1.

```
Algorithm 1 RittReduction
Require: \(p \in R, Q \subset R\); a finite set and \(>\); a ranking
Ensure: \(r\); a remainder of \(p\) on division by \(Q\)
    \(h:=p\);
    \(r:=0\);
    while \(h \neq 0\) do
        if there is some \(q \in Q\) and \(\theta \in \Theta\) with \(\operatorname{rank}(h)=\operatorname{rank}(\theta q)\) then
            \(h:=h-\frac{\operatorname{in}(h)}{\operatorname{in}(q)} \theta q ;\)
        else
            \(r:=r+\operatorname{in}(h) \operatorname{rank}(h) ;\)
            \(h:=h-\operatorname{in}(h) \operatorname{rank}(h) ;\)
        end if
    end while
    Return ( \(r\) )
```

Proof. The termination of this algorithm follows from the well-ordering property of > (cf. [20]). Namely as one observes, the rank of $h$ decreases as one goes along the steps of the algorithm and hence, it terminates after a finitely many steps, when we will have $h=0$.

Now let us consider the correctness of the algorithm. For this, we claim that the equality:

$$
\begin{equation*}
p=\left(\sum_{q \in Q} c_{q} \theta_{q} q\right)+h+r \tag{5}
\end{equation*}
$$

holds at each step of the algorithm. If we prove this claim then, the final value $h=0$ of $h$ can concludes the assertion. To prove the claim, we consider two cases:

Case 1: If a division occurs by a polynomial, say $q_{i}$, then the right hand side of (5) is equal to:

$$
\left.\left(\sum_{q \in Q} c_{q} \theta_{q} q+c \theta_{q_{i}} q_{i}\right)+\left(h-c \theta_{q_{i}} q_{i}\right)\right)+r
$$

with $c=\operatorname{in}\left(q_{i}\right) / \operatorname{in}(h)$. Therefore, it visibly is still equal to $p$.
Case 2: If no division arises, then the right hand side of (5) is equal to:

$$
\sum_{q \in Q} c_{q} \theta_{q} q+(h-\operatorname{in}(h) \operatorname{rank}(h))+(r+\operatorname{in}(h) \operatorname{rank}(h)),
$$

and this is also equal to $p$.
In both cases, the equation (5) is satisfied at each step of the algorithm. Moreover, one convinces oneself that the last two assertions of the Theorem hold according to the structure of this algorithm.

One should notice that, as long as the field $K$ is the one of real numbers $\mathbb{R}$, then the above version of the Ritt's reduction algorithm works as well to compute the remainder of the division of a LinCons differential polynomial by a finite system of LinCons PDE's. However, the coefficients of the PDE systems that we consider in this paper belong to the field $\mathbb{C}=\mathbb{R}(i)$ with $i=\sqrt{-1}$. In this case, we need to perform also the complex conjugation to obtain a full remainder. For this, we need the following definition and theorem.

Definition 3.2. Let $R:=\mathbb{C}\left\{u_{1}, \ldots, u_{n}\right\}$ be a differential polynomial ring with $u_{j}=\operatorname{Re}\left(u_{j}\right)+i \operatorname{Im}\left(u_{j}\right)$ for $j=1, \ldots, n$ as the unknown functions. We define the bar operation $-: R \rightarrow R$ by:

- $\operatorname{Re}(a)+i \operatorname{Im}(a)=\operatorname{Re}(a)-i \operatorname{Im}(a)$ for each $a \in \mathbb{C}$,
- $\overline{\operatorname{Re}\left(u_{j}\right)+i \operatorname{Im}\left(u_{j}\right)}=\operatorname{Re}\left(u_{j}\right)-i \operatorname{Im}\left(u_{j}\right)$ for each $j=1, \ldots, n$.

As a matter of fact, the bar operator is compatible with the derivations; namely, for each (real) $\theta \in \Theta$ and each $j=1, \ldots, n$, one has:

$$
\overline{\theta u_{j}}=\theta \overline{u_{j}} .
$$

This allows one to insert the bar reduction operator in the Ritt's reduction algorithm.

Theorem 3.2. (Extended Ritt's reduction theorem) Consider a differential polynomial ring $R=\mathbb{C}\left\{u_{1}, \ldots, u_{n}\right\}$ over the field of complex numbers, let $\Theta$ be the set of its derivation operators, and let ' $>$ ' be a ranking over $\Theta U$. Furthermore, assume that $p \in R$ is a LinCons differential polynomial and let $Q$ be a finite
set of LinCons differential polynomials. Then, there exists $r \in R$, and for each $q \in Q$, there exists $\theta_{q}, \theta_{\bar{q}} \in \Theta$ and $c_{q}, c_{\bar{q}} \in K$ satisfying the following conditions:

- $p=\left(\sum_{q \in Q} c_{q} \theta_{q} q\right)+\left(\sum_{q \in Q} c_{\bar{q}} \theta_{\bar{q}} \bar{q}\right)+r$,
- for each $q$ appearing in this summation we have:

$$
\operatorname{rank}(r)<\min _{>}\left\{\operatorname{rank}\left(\theta_{q} q\right), \operatorname{rank}\left(\theta_{\bar{q}} \bar{q}\right)\right\},
$$

- no term of $r$ is a derivation of either $\operatorname{rank}(q)$ or $\operatorname{rank}(\bar{q})$ for each $q \in Q$.

Here, the differential polynomial $r$ is called the full-remainder of $p$ on division by $Q$. The proof of this Theorem is similar to that of Theorem 3.1. Let us display the following algorithm like Algorithm 1 extended by the bar reduction.

```
Algorithm 2 ExtendedRittReduction
Require: \(p \in R, Q \subset R\); a finite set and \(>\); a ranking
Ensure: \(r\); a remainder of \(p\) on division by \(Q\)
    \(h:=p\);
    \(r:=0\);
    while \(h \neq 0\) do
        if there is some \(q \in Q\) and \(\theta \in \Theta\) with \(\operatorname{rank}(h)=\operatorname{rank}(\theta q)\) then
            \(h:=h-\frac{\operatorname{in}(h)}{\operatorname{in}(q)} \theta q ;\)
        else
            if there is some \(q \in Q\) and \(\theta \in \Theta\) with \(\operatorname{rank}(h)=\operatorname{rank}(\theta \bar{q})\) then
                \(h:=h-\frac{\operatorname{in}(h)}{\operatorname{in}(q)} \theta \bar{q} ;\)
            else
                    \(r:=r+\operatorname{in}(h) \operatorname{rank}(h) ;\)
                \(h:=h-\operatorname{in}(h) \operatorname{rank}(h) ;\)
            end if
        end if
    end while
    Return ( \(r\) )
```

3.2. Rosenfeld-Gröbner algorithm. As mentioned before, to solve a PDE system $\Sigma$, we use the Rosenfeld-Gröbner algorithm to decompose the radical of [ $\Sigma$ ], into some new PDE systems, presented by explicit generators. These generators have novel properties which leads to do a complete analysis of $\Sigma$. The main Rosenfeld-Gröbner algorithm as presented in [10,9] requires some recursive loops to construct the mentioned decomposition. However, as we consider the RosenfeldGröbner algorithm in the special case of the LinCons PDE systems, there is no need longer to decompose the differential ideal generated by the system into regular differential ideals. So, it is convenient to provide an adapted and computationally simpler version of the Rosenfeld-Gröbner algorithm to deal with just LinCons pDEs. Let us call this algorithm by $L R G$ which stands for the Lincons RosenfeldGröbner algorithm. First, we need the definition of $\Delta$-polynomial - similar in spirit to that in Gröbner bases theory - which plays a crucial role.

Definition 3.3. Consider two LinCons differential polynomials $p_{1}$ and $p_{2}$ with $\operatorname{ld}\left(p_{i}\right)=\theta_{i} u_{i}, i=1,2$. Then, the $\Delta$-polynomial of $p_{1}$ and $p_{2}$ is defined as:

$$
\Delta\left(p_{1}, p_{2}\right)= \begin{cases}\operatorname{lc}\left(p_{2}\right) \frac{\theta_{1,2}}{\theta_{1}} p_{1}-\operatorname{lc}\left(p_{1}\right) \frac{\theta_{1,2}}{\theta_{2}} p_{2} & u_{1}=u_{2} \\ 0 & u_{1} \neq u_{2}\end{cases}
$$

where $\theta_{1,2}=\operatorname{lcd}\left(\theta_{1}, \theta_{2}\right)$.
The aim of calculating the $\Delta$-polynomial of two differential polynomials is in fact to remove their leading derivatives to obtain (probably) a new leading derivative.

Now, let us describe the LRG algorithm. If $\Sigma \subset R$ is a subset of a differential ring $R$ (in fact, a PDE system) then, $[\Sigma]$ denotes the smallest differential ideal of $R$, containing $\Sigma$ and closed under complex conjugation.

```
Algorithm 3 LRG algorithm
Require: \(\Sigma\); a finite set of LinCons differential polynomials, \(>\); a ranking
Ensure: \(G\); a canonical representative for \([\Sigma]\)
    \(G:=\Sigma\);
    \(P:=\left\{\left\{p_{1}, p_{2}\right\} \mid p_{1}, p_{2} \in G\right\} ;\)
    while \(P \neq\{ \}\) do
        Select and remove \(\left\{p_{1}, p_{2}\right\} \in P\);
        \(h:=\Delta\left(p_{1}, p_{2}\right)\);
        \(r:=\) ExtendedRittReduction \((h, G,>)\);
        if \(r \neq 0\) then
            \(P:=P \cup\{\{r, g\} \mid g \in G\} ;\)
            \(G:=G \cup\{r\} ;\)
        end if
    end while
    Return ( \(G\) )
```

The following theorem shows the termination and correctness of the algorithm.
Theorem 3.3. The following statements hold:
(a) LRG algorithm terminates in a finite number of steps.
(b) If $G$ is the canonical representative of $[\Sigma]$ then, any full-remainder of a LinCons differential polynomial $p \in R$ on division by $G$ is zero if and only if $p \in[\Sigma]$.

Proof. (a) The termination of the algorithm is guaranteed by the Ritt-Raudenbush basis Theorem (the analogue of the Hilbert basis theorem for polynomial rings). According to this theorem, since $K=\mathbb{C}$ is Noetherian with respect to the radical differential ideals, then $R$ is too (cf. [20]).

Now, using reductio ad absurdum, let us assume that the algorithm does not terminate for a finite set $\Sigma$. Thus, we have an ascending chain of ideals $\left[\Sigma_{1}\right] \subset$ $\left[\Sigma_{2}\right] \subset \cdots$ which does not stabilize where $\Sigma_{i}$ is the set of leading derivatives of the differential polynomials at the $i$-th step of the execution of the algorithm (by the $i$-th step we mean computing the $i$-th new polynomial and adding it to $G$ ). One can observe that $\Sigma_{i}$ contains LinCons polynomials and therefore $\left[\Sigma_{i}\right]$ is a radical
ideal, namely a radical differential ideal ${ }^{2}$. This contradicts the Noetherianity of $R$ and so, proves the termination.
(b) To prove the correctness of the algorithm, it is sufficient to show that if $p \in[\Sigma]$ is a LinCons differential polynomial then its full-remainder on division by $G$ is zero. Since $p \in[\Sigma]$, then one can conclude by Rosenfeld's Lemma (see [20], Chap. III, Sect. 8, Lemma 5), that a partial remainder of $p$, say $p^{\prime}$, on division by $G$ belongs to $(\Sigma \cup \bar{\Sigma})$. On the other hand, the set of $\Delta$-polynomials contains also S-polynomials (cf. [3]) - note that the polynomials, under consideration in this paper, are LinCons. Moreover, in ExtendedRittreduction algorithm, we consider the complex conjugation of any computed polynomial. These imply that

$$
\operatorname{EXTENDEDRITTREDUCTION}\left(p^{\prime}, G,>\right)=0
$$

according to the Buchberger's criterion (see [3], Theorem 5.48). Therefore, any full-remainder of $p$ will be equal to zero.

At the end of this section, let us illustrate with the help of an example, how one can employ the MAPLE package DifferentialAlgebra ${ }^{3}$ to handle and solve a LinCons PDE system.

Example 3.4. Consider the following LinCons PDE system $\Sigma \subset \mathbb{Q}(x, y)[u, v]$ :

$$
\Sigma:=\left\{\begin{aligned}
\frac{\partial^{2}}{\partial y^{2}} u(x, y)-\frac{\partial^{2}}{\partial x^{2}} v(x, y)-\frac{\partial^{2}}{\partial x \partial y} v(x, y) & =0 \\
\frac{\partial^{2}}{\partial x^{2}} v(x, y)-\frac{\partial^{2}}{\partial y^{2}} v(x, y)+v(x, y) & =0 \\
\frac{\partial^{2}}{\partial x^{2}} u(x, y)-\frac{\partial^{2}}{\partial x \partial y} u(x, y) & =0
\end{aligned}\right.
$$

where $\mathbb{Q}(x, y)$ is the field of fractions of the polynomial ring $\mathbb{Q}[x, y]$. First, we must call the desired package to make it available:

```
[> with(DifferentialAlgebra);
```

and continue with the following three steps.
Step 1. In this step, we set:

$$
\Sigma:=\left\{p_{1}:=u_{y, y}-v_{x, x}-v_{x, y}, \quad p_{2}:=v_{x, x}-v_{y, y}+v, \quad p_{3}:=u_{x, x}-u_{x, y}\right\}
$$

Furthermore, we define the differential ring $\mathbb{Q}(x, y)[u, v]$ equipped with a ranking as follows.
[> R:=DifferentialRing(blocks=[[u, v]], derivations=[x, y]);
This ring has $u, v$ as unknown functions of the variables $x, y$ and also, it admits the set of derivations $\Delta=\left\{\frac{\partial}{\partial x}, \frac{\partial}{\partial y}\right\}$. Moreover, here the picked ranking is orderly, namely the following statement holds:

$$
\theta u<\delta v \Leftrightarrow \operatorname{ord} \theta<\operatorname{ord} \delta
$$

for two arbitrary elements $\delta, \theta$ of $\Theta=\left\{\frac{\partial^{i+j}}{\partial x^{i} \partial y^{j}}, \quad i, j \in \mathbb{N}\right\}$.
Step 2. Next, we employ the Rosenfeld-Gröbner algorithm to compute a canonical representative for $[\Sigma]$, :
[> CP := RosenfeldGroebner ([p1, p2, p3], R);
Now to see the equations of, for example, the first component of $C P$, we enter the following command:

[^1]```
[> Equations(CP[1]);
```

The result of this line is:

$$
\left\{u_{x, x}-u_{x, y}, u_{y, y}-v_{x, y}, v_{x, x}, v_{y, y}-v\right\} .
$$

Step 3. Finally, we find the formal power series solutions corresponding to the functions $u, v$ around the point $(0,0)$, up to the order 3 :

PowerSeriesSolution (CP, order = 3);
and as the results it returns:

$$
\begin{aligned}
u(x, y)= & u(0,0)+u_{y}(0,0) y+u_{x}(0,0) x+1 / 2 v_{x, y}(0,0) y^{2}+ \\
& +u_{x, y}(0,0) x y+1 / 2 u_{x, y}(0,0) x^{2}+1 / 6 u_{x}(0,0) y^{3} \\
v(x, y)= & v(0,0)+v_{y}(0,0) y+v_{x}(0,0) x+1 / 2 v(0,0) y^{2}+ \\
& +v_{x, y}(0,0) x y+1 / 6 v_{y}(0,0) y^{3}+1 / 2 v_{x}(0,0) x y^{2}
\end{aligned}
$$

which is in fact the solution set of the above PDE system $\Sigma$.
Remark 3.5. It is worth noting that, if a PDE system contains some complex conjugates of unknown functions, then we can use only the Maple package DifferentialAlgebra and without implementing LRG algorithm to analyze it. For this purpose, we associate to each unknown function a tag variable as its complex conjugate, and we add it in the definition of the base differential ring. Furthermore, we add the complex conjugate of each input differential polynomial to $\Sigma$. Then, the result of this approach is the same as the output of LRG algorithm. However, the complexity of this computation is growing (and higher than LRG algorithm) when we add a new tag variable.

## 4. InFinitesimal Lie algebra of REAL ANALYTIC CR-GENERIC SUBMANIFOLDS

4.1. Effective tangency equations. Hereafter, by $M \subset \mathbb{C}^{n+k}$ we mean a real analytic CR-generic submanifold of CR-dimension $n$ and of codimension $k$; recall ( $[2,24]$ ) that CR-genericity means that $T M+J T M=\left.T \mathbb{C}^{n+k}\right|_{M}$, where $J$ is the standard complex structure (multiplication by $i$ ). In order to compute $\mathfrak{a u t}_{C R}(M)$ for an explicitly given such submanifold $M \subset \mathbb{C}^{n+k}$, it is most convenient to work with complex defining equations of the specific shape ([24, 1, 25]):

$$
\bar{w}_{j}+w_{j}=\bar{\Xi}_{j}(\bar{z}, z, w) \quad(j=1 \cdots k)
$$

where the coordinates $(z, w)=\left(z_{1}, \ldots, z_{n}, w_{1}, \ldots, w_{k}\right)$ are centered at the origin $0 \in M$ and where $T_{0} M=\left\{\bar{w}_{j}+w_{j}=0: j=1, \ldots, k\right\}$, so that all $\bar{\Xi}_{j}=\mathrm{O}(2)$.

A general $(1,0)$ vector field having holomorphic coefficients:

$$
\mathrm{X}=\sum_{i=1}^{n} Z^{i}(z, w) \frac{\partial}{\partial z_{i}}+\sum_{l=1}^{k} W^{l}(z, w) \frac{\partial}{\partial w_{l}}
$$

is called an infinitesimal $C R$-automorphism of $M$, whenever it is tangent to it, namely whenever $\left.(\mathrm{X}+\overline{\mathrm{X}})\right|_{\mathrm{M}} \equiv 0$. Concretely and more precisely, the condition that a holomorphic vector field X belongs to $\mathfrak{a u t}_{C R}(M)$ means that for $j=1, \ldots, k$,
the differentiated equation:

$$
\begin{aligned}
0=(\overline{\mathrm{X}}+\mathrm{X}) & {\left[\bar{w}_{j}+w_{j}-\bar{\Xi}_{j}(\bar{z}, z, w)\right]=} \\
= & \overline{\mathrm{X}}\left[\bar{w}_{j}+w_{j}-\bar{\Xi}_{j}(\bar{z}, z, w)\right]+\mathrm{X}\left[\bar{w}_{j}+w_{j}-\bar{\Xi}_{j}(\bar{z}, z, w)\right] \\
= & \bar{W}^{j}(\bar{z}, \bar{w})-\sum_{i=1}^{n} \bar{Z}^{i}(\bar{z}, \bar{w}) \frac{\partial \bar{\Xi}_{j}}{\partial \bar{z}_{i}}(\bar{z}, z, w)+ \\
& \quad+W^{j}(z, w)-\sum_{i=1}^{n} Z^{i}(z, w) \frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w)-\sum_{l=1}^{k} W^{l}(z, w) \frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}(\bar{z}, z, w)
\end{aligned}
$$

should vanish for every $(z, w) \in M$. On the other hand, this condition holds if and only if, after extrinsic complexification and replacement of $\bar{w}$ by $-w+\bar{\Xi}(\bar{z}, z, w)$, the $k$ power series obtained in $\mathbb{C}\{\bar{z}, z, w\}$ vanish identically, and this yields the tangency equations:

$$
\begin{gather*}
0 \equiv \bar{W}^{j}(\bar{z},-w+\bar{\Xi}(\bar{z}, z, w))-\sum_{i=1}^{n} \bar{Z}^{i}(\bar{z},-w+\bar{\Xi}(\bar{z}, z, w)) \frac{\partial \bar{\Xi}_{j}}{\partial \bar{z}_{i}}(\bar{z}, z, w)+ \\
+W^{j}(z, w)-\sum_{i=1}^{n} Z^{i}(z, w) \frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w)-\sum_{l=1}^{k} W^{l}(z, w) \frac{\partial \bar{\Xi}_{j}}{\partial w}(\bar{z}, z, w)  \tag{6}\\
(j=1, \ldots, k) .
\end{gather*}
$$

Proposition 4.1. The holomorphic vector field:

$$
X=\sum_{i=1}^{n} Z^{i}(z, w) \frac{\partial}{\partial z_{i}}+\sum_{l=1}^{k} W^{l}(z, w) \frac{\partial}{\partial w_{l}}
$$

is an infinitesimal $C R$-automorphism of a generic real analytic CRgeneric submanifold $M \subset \mathbb{C}^{n+k}$ represented in coordinates $(z, w)=$ $\left(z_{1}, \ldots, z_{n}, w_{1}, \ldots, w_{k}\right)$ as the graph of the $k$ complex defining functions:

$$
w_{j}+\bar{w}_{j}=\bar{\Xi}_{j}(\bar{z}, z, w) \quad(j=1, \ldots, k)
$$

if and only if its coefficients $Z^{i}(z, w)$ and $W^{l}(z, w)$ satisfy the $k$ equations (6).
4.2. General formulae. According to Proposition 4.1, to find the infinitesimal CR-automorphisms $X$ associated to a CR-generic submanifold $M$ of $\mathbb{C}^{n+k}$, it is necessary and sufficient to determine the holomorphic functions $Z^{i}(z, w)$ and $W^{l}(z, w)$ satisfying the tangency equations (6). Then, the main question that immediately arises here is to ask: How can one specify such functions? To answer this question, we focus our attention on providing an effective algorithm. To this aim, first we introduce the expansions of the coefficients of such a sought $X$ with respect to the powers of $z$ :

$$
\begin{equation*}
Z^{i}(z, w)=\sum_{\alpha \in \mathbb{N}^{n}} z^{\alpha} Z^{i, \alpha}(w) \quad \text { and } \quad W^{l}(z, w)=\sum_{\alpha \in \mathbb{N}^{n}} z^{\alpha} W^{l, \alpha}(w) \tag{7}
\end{equation*}
$$

where the $Z^{i, \alpha}(w)$ and the $W^{l, \alpha}(w)$ are local holomorphic functions. We will show that the identical vanishing of the $k$ equations (6) in $\mathbb{C}\{\bar{z}, z, w\}$ is equivalent to a certain (in general complicated) linear system of partial differential equations involving the $\frac{\partial|\gamma| Z^{k, \alpha}}{\partial w^{\gamma}}(w)$, the $\frac{\partial\left|\gamma^{\prime}\right| Z^{k^{\prime}, \alpha^{\prime}}}{\partial w^{\gamma^{\prime}}}(w)$, the $\frac{\partial\left|\gamma^{\prime \prime}\right| W^{l, \alpha^{\prime \prime \prime}}}{\partial w^{\gamma^{\prime \prime}}}(w)$ and the $\frac{\partial^{\left|\gamma^{\prime \prime \prime}\right|} \mid W^{l^{\prime}, \alpha^{\prime \prime \prime}}}{\partial w^{\gamma^{\prime \prime \prime}}}(w)$.

Inserting these expansions with respect to the powers of $z$ in the tangency equations (6), we get:

$$
\begin{aligned}
0 \equiv & \sum_{\alpha \in \mathbb{N}^{n}} \bar{z}^{\alpha} \bar{W}^{j, \alpha}(-w+\bar{\Xi})-\sum_{i=1}^{n} \sum_{\alpha \in \mathbb{N}^{n}} \bar{z}^{\alpha} \bar{Z}^{i, \alpha}(-w+\bar{\Xi}) \frac{\partial \bar{\Xi}_{j}}{\partial \bar{z}_{i}}(\bar{z}, z, w)+ \\
& +\sum_{\beta \in \mathbb{N}^{n}} z^{\beta} W^{j, \beta}(w)-\sum_{i=1}^{n} \sum_{\beta \in \mathbb{N}^{n}} z^{\beta} Z^{i, \beta}(w) \frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w)-\sum_{l=1}^{k} \sum_{\beta \in \mathbb{N}^{n}} z^{\beta} W^{l, \beta}(w) \frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}(\bar{z}, z, w) .
\end{aligned}
$$

Since in these equations, $w$ is the argument both of all the $Z^{i, \beta}$ and of all the $W^{l, \beta}$ appearing in the second line, one should arrange that the same argument $w$ takes place inside the functions $\bar{W}^{j, \alpha}$ and $\bar{Z}^{i, \alpha}$ appearing in the first line. Thus, one is led, for an arbitrary converging holomorphic power series $\bar{A}=\bar{A}(w)=$ $\sum_{\gamma \in \mathbb{N}^{k}} \frac{\partial^{|\gamma| \bar{A}}}{\partial w^{\gamma}}(0) w^{\gamma}$, to apply the well known basic infinite Taylor series formulae under the following slightly artificial form:

$$
\begin{align*}
\bar{A}(-w+\bar{\Xi}) & =\bar{A}(w+(-2 w+\bar{\Xi})) \\
& =\sum_{\gamma \in \mathbb{N}^{k}} \frac{\partial^{|\gamma|} \bar{A}}{\partial w^{\gamma}}(w) \frac{1}{\gamma!}(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma} . \tag{8}
\end{align*}
$$

When one does this, one transforms the first lines of the previous $k$ equations as follows:

$$
\begin{align*}
& 0 \equiv \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\gamma \in \mathbb{N}^{k}} \frac{1}{\gamma!} \bar{z}^{\alpha}(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma} \frac{\partial^{|\gamma|} \bar{W}^{j, \alpha}}{\partial w^{\gamma}}(w)-  \tag{9}\\
&-\sum_{i=1}^{n} \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\gamma \in \mathbb{N}^{k}} \frac{1}{\gamma!} \bar{z}^{\alpha}(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma} \frac{\partial^{|\gamma|} \bar{Z}^{i, \alpha}}{\partial w^{\gamma}}(w)+ \\
&+\sum_{\beta \in \mathbb{N}^{n}} z^{\beta} W^{j, \beta}(w)-\sum_{i=1}^{n} \sum_{\beta \in \mathbb{N}^{n}} z^{\beta} Z^{i, \beta}(w) \frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w)-\sum_{l=1}^{k} \sum_{\beta \in \mathbb{N}^{n}} z^{\beta} W^{l, \beta}(w) \frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}(\bar{z}, z, w) \\
&(j=1 \cdots k) .
\end{align*}
$$

But still, we must expand and reorganize everything in terms of the powers $\bar{z}^{\alpha} z^{\beta}$ of $(\bar{z}, z)$. At first, we must do this for the multipowers:

$$
(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma}=\prod_{j=1}^{k}\left(-2 w_{j}+\bar{\Xi}_{j}(\bar{z}, z, w)\right)^{\gamma_{j}}
$$

4.3. Expansion, reorganization and associated LinCons PDE system. To begin with, let us denote the $(\bar{z}, z)$-power series expansion of $-2 w_{j}+\bar{\Xi}_{j}$ by:

$$
\begin{equation*}
-2 w_{j}+\bar{\Xi}_{j}(\bar{z}, z, w)=\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w) \quad(j=1 \cdots k) \tag{10}
\end{equation*}
$$

with the understanding that the coefficients of the expansion of $\bar{\Xi}_{j}$ would be denoted plainly $\bar{\Xi}_{j, \alpha, \beta}(w)$, without $\sim$ sign. Reminding $\bar{\Xi}_{j}=\mathrm{O}(2)$, we adopt the convention that in this right-hand side, the $\bar{\Xi}_{j, \alpha, \beta}^{\sim}(w)$ for $\alpha=\beta=0$ comes not from $\bar{\Xi}_{j}$ itself, but just from the supplementary first-order term $-2 w_{j}$.

Thus, denoting:

$$
\gamma=\left(\gamma_{1}, \gamma_{2}, \ldots, \gamma_{k}\right) \in \mathbb{N}^{k}
$$

we may expand explicitly the exponentiated product under consideration, and the intermediate, detailed computations read as follows:

$$
\begin{aligned}
& \prod_{j=1}^{k}\left(-2 w_{j}+\bar{\Xi}_{j}(\bar{z}, z, w)\right)^{\gamma_{j}}= \\
& =\prod_{j=1}^{k}\left(\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w)\right)^{\gamma_{j}} \\
& =\prod_{j=1}^{k}\left[\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left(\sum_{\substack{\alpha_{1}+\ldots+\alpha_{\gamma_{j}}=\alpha \\
\beta_{1}+\cdots+\gamma_{\gamma_{j}}=\beta}} \Xi_{j, \alpha_{1}, \beta_{1}}^{\sim}(w) \cdots \bar{\Xi}_{j, \alpha_{\gamma_{j}}, \beta_{\gamma_{j}}}^{\sim}(w)\right)\right]
\end{aligned}
$$

$$
\begin{aligned}
& \left.\bar{\Xi}_{1, \alpha_{1}^{\alpha}, \beta_{1}^{1}}^{\sim}(w) \cdots \bar{\Xi}_{1, \alpha_{\gamma_{1}}^{1}, \beta_{\gamma_{1}}^{1}}^{\sim}(w) \cdots \cdots \bar{\Xi}_{k, \alpha_{1}^{k}, \beta_{1}^{k}}^{\sim}(w) \cdots \bar{\Xi}_{k, \alpha_{\gamma_{k}}^{k}, \beta_{\gamma_{k}}^{k}}^{\sim}(w)\right] \\
& =: \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \mathcal{A}_{\alpha, \beta, \gamma}\left(\left\{\bar{\Xi}_{\hat{\bar{j}}, \widehat{\beta}}, \widehat{\beta}(w)\right\}_{\hat{j} \in \mathbb{N}, \widehat{\alpha} \in \mathbb{N}^{n}, \widehat{\beta} \in \mathbb{N}^{n}}\right),
\end{aligned}
$$

where we introduce a collection of certain polynomial functions $\mathcal{A}_{\alpha, \beta, \gamma}$ of all the $\overline{\bar{\Xi}}_{\widehat{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)$ that appear naturally in the large brackets of the penultimate equality, namely where we set:

$$
\begin{aligned}
& \mathcal{A}_{\alpha, \beta, \gamma}\left(\left\{\overline{\bar{j}}_{\hat{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}_{\widehat{j} \in \mathbb{N}, \widehat{\alpha} \in \mathbb{N}^{n}, \widehat{\beta} \in \mathbb{N}^{n}}\right):=\sum_{\substack{\alpha_{1}^{1}+\ldots+\alpha^{k}=\alpha=\alpha \\
\beta_{1}+\ldots+\beta^{k}=\beta \\
\alpha_{1}^{1}+\ldots+\alpha_{1}^{1}=\alpha^{1} \\
\beta_{1}^{1}+\ldots+\beta_{\gamma_{1}}^{1}=\beta^{1}}} \ldots \sum_{\substack{\alpha_{1}^{k}+\ldots+\alpha_{k}^{k}=\alpha^{k} \\
\beta_{1}^{k}+\ldots+\beta_{\gamma_{k}}^{k}=\beta_{k}}} \\
& \bar{\Xi}_{1, \alpha_{1}^{1}, \beta_{1}^{1}}^{\sim}(w) \cdots \bar{\Xi}_{1, \alpha_{\gamma_{1}}^{1}, \beta_{\gamma_{1}}^{1}}^{\sim}(w) \cdots \cdots \bar{\Xi}_{k, \alpha_{1}^{k}, \beta_{1}^{k}}^{\sim}(w) \cdots \overline{\bar{\Xi}}_{k, \alpha_{\gamma_{k}}^{k}, \beta_{\gamma_{k}}^{k}}^{\sim}(w) .
\end{aligned}
$$

At present, coming back to the $k$ equations (9) we left momentarily untouched, we see that in them, five sums are extant and we now want to expand and to reorganize properly each one of these sums as a $(\bar{z}, z)$-power series of the form:

$$
\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left(\text { coeff }_{j, \alpha, \beta}\right) .
$$

For the sum in (9), we therefore compute, changing in advance the index $\alpha$ to $\alpha^{\prime}$ :

$$
\begin{align*}
& \sum_{\alpha^{\prime} \in \mathbb{N}^{n}} \sum_{\gamma \in \mathbb{N}^{k}} \frac{1}{\gamma!} \bar{z}^{\alpha^{\prime}} \frac{\partial^{|\gamma|} \frac{\bar{W}^{j}, \alpha^{\prime}}{\partial w^{\gamma}}(w)(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma}=}{} \\
& =\sum_{\alpha^{\prime} \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \frac{1}{\gamma!} \bar{z}^{\alpha^{\prime}} \frac{\partial^{\mid \gamma} \mid \bar{W}^{j, \alpha^{\prime}}}{\partial w^{\gamma}}(w) \sum_{\alpha^{\prime \prime} \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha^{\prime \prime}} z^{\beta} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\bar{\Xi} \tilde{\tilde{j}, \widehat{\alpha}, \widehat{\beta}} \sim_{\widetilde{\beta}}(w)\right\}\right)  \tag{11}\\
& =\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left[\sum_{\gamma \in \mathbb{N}^{k}} \sum_{\alpha=\alpha^{\prime}+\alpha^{\prime \prime}} \frac{1}{\gamma!} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\bar{\Xi}_{\tilde{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}\right) \cdot \frac{\partial^{|\gamma|} \bar{W}^{j}, \alpha^{\prime}}{\partial w^{\gamma}}(w)\right] \text {. }
\end{align*}
$$

The computations for the second sum in (9) are the same:

$$
\begin{aligned}
& -\sum_{i=1}^{n} \sum_{\alpha^{\prime} \in \mathbb{N}^{n}} \sum_{\gamma \in \mathbb{N}^{k}} \frac{1}{\gamma!} \bar{z}^{\alpha^{\prime}} \frac{\partial^{|\gamma|} \bar{Z}^{i, \alpha^{\prime}}}{\partial w^{\gamma}}(w)(-2 w+\bar{\Xi}(\bar{z}, z, w))^{\gamma} \\
(12)= & -\sum_{i=1}^{n} \sum_{\alpha^{\prime} \in \mathbb{N}^{n}} \sum_{\gamma \in \mathbb{N}^{k}} \frac{1}{\gamma!} \bar{z}^{\alpha^{\prime}} \frac{\partial^{|\gamma|} \bar{Z}^{i, \alpha^{\prime}}}{\partial w^{\gamma}}(w) \sum_{\alpha^{\prime \prime} \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha^{\prime \prime}} z^{\beta} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\bar{\Xi}_{\tilde{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}\right) \\
= & \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left[-\sum_{i=1}^{n} \sum_{\gamma \in \mathbb{N}^{k}} \sum_{\alpha^{\prime}+\alpha^{\prime \prime}=\alpha} \frac{1}{\gamma!} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\overline{\left.\left.\left.\bar{\Xi}_{\hat{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}\right) \cdot \frac{\partial^{|\gamma|} \bar{Z}^{i, \alpha^{\prime}}}{\partial w^{\gamma}}(w)\right] .}\right.\right.\right.
\end{aligned}
$$

The third sum in (9) is already almost well written, for we indeed have, if we denote by $\mathbf{0}=(0, \ldots, 0) \in \mathbb{N}^{n}$ the zero-multiindex:

$$
\begin{equation*}
\sum_{\beta \in \mathbb{N}^{n}} z^{\beta} W^{j, \beta}(w)=\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left[\delta_{\alpha}^{0} \cdot W^{j, \beta}(w)\right], \tag{13}
\end{equation*}
$$

where $\delta_{\mathrm{a}}^{\mathrm{b}}=0$ if $\mathrm{a} \neq \mathrm{b}$ and equals 1 if $\mathrm{a}=\mathrm{b}$. To transform the fourth sum in (9), we must at first compute, for each $i=1, \ldots, n$ (and for each $j=1, \ldots, k$ ), the first-order partial derivatives $\frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}$ from (10), which gives, if we denote simply by $\mathbf{1}_{i}$ the multiindex $(0, \ldots, 1, \ldots, 0)$ of $\mathbb{N}^{n}$ with 1 at the $i$-th place and zero elsewhere:

$$
\begin{aligned}
\frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w) & =\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\substack{\beta \in \mathbb{N}^{n} \\
\beta_{i} \geqslant 1}} \bar{z}^{\alpha} \beta_{i} z^{\beta-\mathbf{1}_{i}} \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w) \\
& =\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left(\beta_{i}+1\right) \bar{\Xi}_{j, \alpha, \beta+\mathbf{1}_{i}}^{\sim}(w) .
\end{aligned}
$$

Thanks to this, the fourth sum in (9) may be reorganized as wanted:

$$
\begin{align*}
& -\sum_{i=1}^{n} \sum_{\beta^{\prime} \in \mathbb{N}^{n}} z^{\beta^{\prime}} Z^{i, \beta^{\prime}}(w) \frac{\partial \bar{\Xi}_{j}}{\partial z_{i}}(\bar{z}, z, w)= \\
& =-\sum_{i=1}^{n} \sum_{\beta^{\prime} \in \mathbb{N}^{n}} z^{\beta^{\prime}} Z^{i, \beta^{\prime}}(w) \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta^{\prime \prime} \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta^{\prime \prime}}\left(1+\beta_{i}^{\prime \prime}\right) \bar{\Xi}_{j, \alpha, \beta^{\prime \prime}+\mathbf{1}_{i}}^{\sim}(w)  \tag{14}\\
& =\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left[-\sum_{i=1}^{n} \sum_{\beta^{\prime}+\beta^{\prime \prime}=\beta}\left(\beta_{i}^{\prime \prime}+1\right) \bar{\Xi}_{j, \alpha, \beta^{\prime \prime}+\mathbf{1}_{i}}^{\sim}(w) \cdot Z^{i, \beta^{\prime}}(w)\right] .
\end{align*}
$$

Lastly, in order to transform the fifth sum in (9), we must at first compute, for each $l=1, \ldots, k$ (and for each $j=1, \ldots, k$ ), the first-order partial derivatives $\frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}$, and to this aim, we start by rewriting from (10):

$$
\bar{\Xi}_{j}(\bar{z}, z, w)=2 w_{j}+\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w),
$$

whence it immediately follows:

$$
\frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}(\bar{z}, z, w)=2 \delta_{j}^{l}+\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \frac{\partial \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w)}{\partial w_{l}} .
$$

Thanks to this, the fifth sum in (9), too, may be reorganized appropriately:

$$
\begin{align*}
& -\sum_{l=1}^{k} \sum_{\beta^{\prime} \in \mathbb{N}^{n}} z^{\beta^{\prime}} W^{l, \beta^{\prime}}(w) \frac{\partial \bar{\Xi}_{j}}{\partial w_{l}}(\bar{z}, z, w)= \\
& =-\sum_{l=1}^{k} \sum_{\beta^{\prime} \in \mathbb{N}^{n}} z^{\beta^{\prime}} W^{l, \beta^{\prime}}(w)\left[2 \delta_{j}^{l}+\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta^{\prime \prime} \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta^{\prime \prime}} \frac{\partial \bar{\Xi}_{j, \alpha, \beta^{\prime \prime}}^{\sim}(w)}{\partial w_{l}}\right]  \tag{15}\\
& =\sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta}\left[-2 \delta_{\alpha}^{0} \cdot W^{j, \beta}(w)-\sum_{l=1}^{k} \sum_{\beta^{\prime}+\beta^{\prime \prime}=\beta} \frac{\partial \overline{\bar{\Xi}}_{j, \alpha, \beta^{\prime \prime}}^{\sim}(w)}{\partial w_{l}} W^{l, \beta^{\prime}}(w)\right] .
\end{align*}
$$

Summing up these five reorganized sums appearing in (9) as a double sum $\sum_{\alpha} \sum_{\beta} \bar{z}^{\alpha} z^{\beta}\left(\right.$ coeff $\left._{j, \alpha, \beta}\right)$, and equating to zero all the obtained coefficients (11), (12), (13), (14) and (15), we deduce the following fundamental statement.

Theorem 4.1. Let $M$ be a local generic real analytic $C R$-generic submanifold of $\mathbb{C}^{n+k}$ having positive codimension $k \geqslant 1$ and positive $C R$ dimension $n \geqslant 1$ which is represented, in local holomorphic coordinates $(z, w)=$ $\left(z_{1}, \ldots, z_{n}, w_{1}, \ldots, w_{k}\right)$ centered at the origin $0 \in M$ by $k$ complex defining equations of the shape:

$$
\bar{w}_{j}+w_{j}=\bar{\Xi}_{j}(\bar{z}, z, w) \quad(j=1 \cdots k)
$$

with $\bar{\Xi}_{j}=\mathrm{O}(2)$, and introduce the power series expansion with respect to the variables $(\bar{z}, z)$ :

$$
-2 w_{j}+\bar{\Xi}_{j}(\bar{z}, z, w)=: \sum_{\alpha \in \mathbb{N}^{n}} \sum_{\beta \in \mathbb{N}^{n}} \bar{z}^{\alpha} z^{\beta} \bar{\Xi}_{j, \alpha, \beta}^{\sim}(w) \quad(j=1 \cdots k)
$$

For every multiindex $\alpha \in \mathbb{N}^{n}$, every multiindex $\beta \in \mathbb{N}^{n}$ and every multiindex $\gamma \in \mathbb{N}^{k}$, introduce also the explicit universal polynomial:

$$
\begin{aligned}
\mathcal{A}_{\alpha, \beta, \gamma}\left(\left\{\bar{\Xi}_{\widehat{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}_{\widehat{j} \in \mathbb{N}, \widehat{\alpha} \in \mathbb{N}^{n}, \widehat{\beta} \in \mathbb{N}^{n}}\right):=\sum_{\substack{\alpha^{1}+\cdots+\alpha^{k}=\alpha \\
\beta_{1}+\cdots+\beta^{k}=\beta}} \sum_{\substack{\alpha_{1}^{1}+\cdots+\alpha_{\gamma_{1}}^{1}=\alpha^{1} \\
\beta_{1}^{1}+\cdots+\beta_{\gamma_{1}}^{1}=\beta^{1}}} \cdots \sum_{\substack{\alpha_{1}^{k}+\cdots+\alpha_{\gamma_{k}}^{k}=\alpha^{k} \\
\beta_{1}^{k}+\cdots+\beta_{\gamma_{k}}^{k}=\beta_{k}}} \\
\bar{\Xi}_{1, \alpha_{1}^{1}, \beta_{1}^{1}}^{\sim}(w) \cdots \bar{\Xi}_{1, \alpha_{\gamma_{1}}^{1}, \beta_{\gamma_{1}}^{1}}^{\sim}(w) \cdots \cdots \bar{\Xi}_{k, \alpha_{1}^{k}, \beta_{1}^{k}}^{\sim}(w) \cdots \bar{\Xi}_{k, \alpha_{\gamma_{k}}^{k}, \beta_{\gamma_{k}}^{k}}^{\sim}(w) .
\end{aligned}
$$

Then a general holomorphic vector field:

$$
\mathbf{X}=\sum_{i=1}^{n} Z^{i}(z, w) \frac{\partial}{\partial z_{i}}+\sum_{l=1}^{k} W^{l}(z, w) \frac{\partial}{\partial w_{l}}
$$

is an infinitesimal $C R$-automorphism of $M$ belonging to $\mathfrak{a u t}_{C R}(M)$, namely it has the property that $\overline{\mathrm{X}}+\mathrm{X}$ is tangent to $M$ if and only if, for every $j=1, \ldots, k$, for every $\alpha \in \mathbb{N}^{n}$ and for every $\beta \in \mathbb{N}^{n}$, the following linear holomorphic partial

## differential equation:

$$
\begin{align*}
& 0 \equiv \sum_{\gamma \in \mathbb{N}^{k}} \sum_{\alpha=\alpha^{\prime}+\alpha^{\prime \prime}} \frac{1}{\gamma!} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\bar{\Xi}_{\bar{j}, \tilde{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}_{\widehat{j} \in \mathbb{N}, \hat{\alpha} \in \mathbb{N}^{n}, \bar{\beta} \in \mathbb{N}^{n}}\right) \cdot \frac{\partial^{|\gamma|} \bar{W}^{j, \alpha^{\prime}}}{\partial w^{\gamma}}(w)- \\
& -\sum_{i=1}^{n} \sum_{\gamma \in \mathbb{N}^{k} k} \sum_{\alpha^{\prime}+\alpha^{\prime \prime}=\alpha} \frac{1}{\gamma!} \mathcal{A}_{\alpha^{\prime \prime}, \beta, \gamma}\left(\left\{\bar{\Xi}_{\tilde{j}, \widehat{\alpha}, \widehat{\beta}}^{\sim}(w)\right\}\right) \cdot \frac{\partial^{|\gamma|} \overline{Z^{i}, \alpha^{\prime}}}{\partial w^{\gamma}}(w)+ \\
& +\delta_{\alpha}^{0} \cdot W^{j, \beta}(w)-  \tag{16}\\
& -\sum_{i=1}^{n} \sum_{\beta^{\prime}+\beta^{\prime \prime}=\beta}\left(\beta_{i}^{\prime \prime}+1\right) \bar{\Xi}_{j, \alpha, \beta^{\prime \prime}+1_{i}}^{\sim}(w) \cdot Z^{i, \beta^{\prime}}(w)- \\
& -2 \delta_{\alpha}^{0} \cdot W^{j, \beta}(w)-\sum_{l=1}^{k} \sum_{\beta^{\prime}+\beta^{\prime \prime}=\beta} \frac{\partial \bar{\Xi}_{j, \alpha, \beta^{\prime \prime}}^{\sim}(w)}{\partial w_{l}} W^{l, \beta^{\prime}}(w)
\end{align*}
$$

which is linear with respect to the partial derivatives:

$$
\frac{\partial^{|\gamma|} Z^{i, \alpha}}{\partial w^{\gamma}}(w), \quad \frac{\partial^{\left|\gamma^{\prime}\right|} \bar{Z}^{i^{\prime}, \alpha^{\prime}}}{\partial w^{\gamma^{\prime}}}(w), \quad \frac{\partial^{\left|\gamma^{\prime \prime}\right|} W^{l, \alpha^{\prime \prime}}}{\partial w^{\gamma^{\prime \prime}}}(w), \quad \frac{\partial^{\left|\gamma^{\prime \prime \prime}\right|} \bar{W}^{l^{\prime}, \alpha^{\prime \prime \prime}}}{\partial w^{\gamma^{\prime \prime \prime}}}(w),
$$

together with its conjugate, are satisfied identically in $\mathbb{C}\{w\}$ by the four families of functions:

$$
Z^{i, \alpha}(w), \quad \bar{Z}^{i^{\prime}, \alpha^{\prime}}(w), \quad W^{l, \alpha^{\prime \prime}}(w), \quad \bar{W}^{l^{\prime}, \alpha^{\prime \prime \prime}}(w) .
$$

depending only upon the $k$ holomorphic variables $\left(w_{1}, \ldots, w_{k}\right)$.
4.4. The main strategy. According to Theorem 4.1, finding the sought infinitesimal CR-automorphisms $X$ is equivalent to solve the linear PDE system constructed by the equations (16) with the unknowns $Z^{i, \alpha}, \bar{Z}^{i^{\prime}, \alpha^{\prime}}, W^{l, \alpha^{\prime \prime}}, \bar{W}^{l^{\prime}, \alpha^{\prime \prime \prime}}$ and afterwards, finding the expressions of the holomorphic coefficients $Z^{i}(z, w)$ and $W^{l}(z, w)$ of X for $i=1, \ldots, n$ and $l=1, \ldots, k$, according to the formulae (7) and thanks to the achieved solution. Then, we can choose the following strategy to compute the desired infinitesimal Lie algebra $\mathfrak{a u t}_{C R}(M)$ associated to a specific real analytic CR-generic manifold $M \subset \mathbb{C}^{n+k}$ :

- Constructing the $k$ fundamental equations (6).
- Expanding these equations according to the formulaes (7), (8) and (10).
- Extracting the coefficients of each $z^{\alpha} \bar{z}^{\beta}$ for $\alpha, \beta \in \mathbb{N}^{n}$ and constituting the linear homogeneous PDE system of the partial differential equations (16), introduced in Theorem 4.1.
- Solving the obtained system by the means of techniques in differential algebra theory.
- Substituting the solution of the PDE system into the formulae (7) to find the holomorphic functions $Z^{i, \alpha}(w)$ and $W^{l, \alpha}(w)$ as the coefficients of the infinitesimal CR-automorphisms $X$.
It is worth noting that the already introduced linear PDE system defined underlying the differential ring:

$$
R:=\mathbb{C}(w)\left[Z^{i, \alpha}, \bar{Z}^{i, \alpha^{\prime}}, W^{l, \alpha^{\prime \prime}}, \bar{W}^{l^{\prime}, \alpha^{\prime \prime \prime}}\right]
$$

admits complex linear equations and hence at the fourth step of the above strategy, it is not possible to employ the Rosenfeld-Gröbner algorithm directly for solving it. But, it is feasible to equip this algorithm with the conjugate operator bar-reduction
for being able to treat the complex equations. Nevertheless, one should notice that such a linear PDE system is not necessarily a LinCons one, since its coefficients may contain some powers of the variables $w_{l}, l=1, \ldots, k$. However, a careful look at the equations (10) and (16) reveals that if the $k$ defining functions $\bar{\Xi}_{i}$ are independent of the variables $w_{1}, \ldots, w_{k}$, then the concerned linear PDE system has constant complex coefficients, namely it will be a LinCons PDE system. Such CRgeneric submanifolds $M \subset \mathbb{C}^{n+k}$ which are defined as the graph of the $k$ defining complex equations:

$$
\bar{w}_{j}+w_{j}=\bar{\Xi}_{j}(\bar{z}, z) \quad(j=1 \cdots k)
$$

are usually called the rigid submanifolds. They constitute a wide and considerably significant class of CR-generic submanifolds (see [2, 24, 5, 8, 25, 26, 30, 31]). Hence, in the case of the rigid real analytic generic CR-generic submanifolds, one can employ the computationally much simpler algorithm $L R G$ (Algorithm 3) to perform the fourth step of the above strategy. In the sequel, using this method, we compute the Lie algebras of infinitesimal CR-automorphisms associated to three rigid real analytic generic CR-generic submanifolds of $\mathbb{C}^{1+8}$.

## 5. LIE ALGEBRA OF INFINITESIMAL CR-AUTOMORPHISMS of CR-GENERIC SUBMANIFOLDS $\mathbb{M}^{1}, \mathbb{M}^{2}$ and $\mathbb{M}^{3}$ of $\mathbb{C}^{1+8}$

The aim of the current section is to compute the Lie algebras of infinitesimal CR-automorphisms, associated to the three rigid real analytic CR-generic submanifolds $\mathbb{M}^{1}, \mathbb{M}^{2}$ and $\mathbb{M}^{3}$ of $\mathbb{C}^{1+8}$ of CR dimension 1 , represented in coordinates $\left(z, w_{1}, \ldots, w_{8}\right)$ by (1). We give in detail the computations of $\mathfrak{a u t} \boldsymbol{u t}_{C R}\left(\mathbb{M}^{1}\right)$ and since the remaining computations of $\mathfrak{a u t} \mathfrak{t}_{C R}\left(\mathbb{M}^{2}\right)$ and $\mathfrak{a u t} \mathfrak{u}_{C R}\left(\mathbb{M}^{3}\right)$ are fairly similar, then shall not report them in detail.

For the first model $\mathbb{M}^{1}$, represented by the eight real analytic equations: (17)

$$
\begin{array}{ll}
w^{1}-\bar{w}^{1}=\Xi_{1}(z, \bar{z}):=2 i z \bar{z}, & w^{2}-\bar{w}^{2}=\Xi_{2}(z, \bar{z}):=2 i\left(z^{2} \bar{z}+z \bar{z}^{2}\right) \\
w^{3}-\bar{w}^{3}=\Xi_{3}(z, \bar{z}):=2\left(z^{2} \bar{z}-z \bar{z}^{2}\right), & w^{4}-\bar{w}^{4}=\Xi_{4}(z, \bar{z}):=2 i\left(z^{3} \bar{z}+z \bar{z}^{3}\right) \\
w^{5}-\bar{w}^{5}=\Xi_{5}(z, \bar{z}):=2\left(z^{3} \bar{z}-z \bar{z}^{3}\right), & w^{6}-\bar{w}^{6}=\Xi_{6}(z, \bar{z}):=2 i z^{2} \bar{z}^{2} \\
w^{7}-\bar{w}^{7}=\Xi_{7}(z, \bar{z}):=2 i\left(z^{4} \bar{z}+z \bar{z}^{4}\right), & w^{8}-\bar{w}^{8}=\Xi_{8}(z, \bar{z}):=2\left(z^{4} \bar{z}-z \bar{z}^{4}\right)
\end{array}
$$

a holomorphic vector field $\mathrm{X}:=Z(z, w) \partial_{z}+\sum_{l=1}^{8} W^{l}(z, w) \partial_{w_{l}}$ is tangent to $\mathbb{M}^{1}$ if and only if the restriction of the real vector filed $X=X+\bar{X}$ to each of the above eight defining equations vanishes identically. In other words, if and only if the holomorphic functions $Z$ and $W^{l}, l=1, \ldots, 8$, and their conjugates enjoy the following eight equations (cf. (6)):

$$
\begin{align*}
& 0 \equiv\left[W^{1}-\bar{W}^{1}-2 i \bar{z} Z-2 i z \bar{Z}\right]_{w=\bar{w}+\Xi} \\
& 0 \equiv\left[W^{2}-\bar{W}^{2}-4 i z \bar{z} Z-2 i \bar{z}^{2} Z-2 i z^{2} \bar{Z}-4 i z \bar{z} \bar{Z}\right]_{w=\bar{w}+\Xi} \\
& 0 \equiv\left[W^{3}-\bar{W}^{3}-4 z \bar{z} Z+2 \bar{z}^{2} Z-2 z^{2} \bar{Z}+4 z \bar{z} \bar{Z}\right]_{w=\bar{w}+\Xi} \\
& 0 \equiv\left[W^{4}-\bar{W}^{4}-6 i z^{2} \bar{z} Z-2 i \bar{z}^{3} Z-2 i z^{3} \bar{Z}-6 i z \bar{z}^{2} \bar{Z}\right]_{w=\bar{w}+\Xi}  \tag{18}\\
& 0 \equiv\left[W^{5}-\bar{W}^{5}-6 z^{2} \bar{z} Z+2 \bar{z}^{3} Z-2 z^{3} \bar{Z}+6 z \bar{z}^{2} \bar{Z}\right]_{w=\bar{w}+\Xi} \\
& 0 \equiv\left[W^{6}-\bar{W}^{6}-4 i z \bar{z}^{2} Z-4 i z^{2} \bar{z} \bar{Z}\right]_{w=\bar{w}+\Xi} \\
& 0 \equiv\left[W^{7}-\bar{W}^{7}-8 i z^{3} \bar{z} Z-2 i \bar{z}^{4} Z-2 i z^{4} \bar{Z}-8 i z \bar{z}^{3} \bar{Z}\right]_{w=\bar{w}+\Xi}
\end{align*}
$$

$$
0 \equiv\left[W^{8}-\bar{W}^{8}-8 z^{3} \bar{z} Z+2 \bar{z}^{4} Z-2 z^{4} \bar{Z}+8 z \bar{z}^{3} \bar{Z}\right]_{w=\bar{w}+\Xi}
$$

These functions are real analytic and hence one may expand them with respect to the powers of $z(c f .(7))$ :

$$
Z(z, w)=\sum_{k \in \mathbb{N}} z^{k} Z_{k}(w) \quad \text { and } \quad W^{l}(z, w)=\sum_{k \in \mathbb{N}} z^{k} W_{k}^{l}(w)
$$

Our current aim is to find a closed form expression for the holomorphic functions $Z(z, w)$ and $W^{l}(z, w)$ by using their corresponding Taylor series. One sees simplified expressions of these functions in the following lemma:

Lemma 5.1. The holomorphic functions $Z(z, w)$ and $W^{l}(z, w), l=1, \ldots, 8$ are all polynomial with respect to $z$ :

$$
\left[\begin{array}{rl}
Z(z, w) & =Z_{0}(w)+z Z_{1}(w)+z^{2} Z_{2}(w)+z^{3} Z_{3}(w)+z^{4} Z_{4}(w)+z^{5} Z_{5}(w) \\
W^{1}(z, w) & =W_{0}^{1}(w)+z W_{1}^{1}(w), \\
W^{2}(z, w) & =W_{0}^{2}(w)+z W_{1}^{2}(w)+z^{2} W_{2}^{2}(w), \\
W^{3}(z, w) & =W_{0}^{3}(w)+z W_{1}^{3}(w)+z^{2} W_{2}^{3}(w), \\
W^{4}(z, w) & =W_{0}^{4}(w)+z W_{1}^{4}(w)+z^{2} W_{2}^{4}(w)+z^{3} W_{3}^{4}(w), \\
W^{5}(z, w) & =W_{0}^{5}(w)+z W_{1}^{5}(w)+z^{2} W_{2}^{5}(w)+z^{3} W_{3}^{5}(w), \\
W^{6}(z, w) & =W_{0}^{6}(w), \\
W^{7}(z, w) & =W_{0}^{7}(w)+z W_{1}^{7}(w)+z^{2} W_{2}^{7}(w)+z^{3} W_{3}^{7}(w)+z^{4} W_{4}^{7}(w), \\
W^{8}(z, w) & =W_{0}^{8}(w)+z W_{1}^{8}(w)+z^{2} W_{2}^{8}(w)+z^{3} W_{3}^{8}(w)+z^{4} W_{4}^{8}(w)
\end{array}\right.
$$

Proof. After expansion, the first equation (18) reads:

$$
\begin{align*}
0 \equiv & \sum_{k \in \mathbb{N}} z^{k}\left[W_{k}^{1}\left(\bar{w}_{1}+\Xi_{1}, \bar{w}_{2}+\Xi_{2}, \ldots, \bar{w}_{8}+\Xi_{8}\right)-\right. \\
& \left.\quad-2 i \bar{z} Z_{k}\left(\bar{w}_{1}+\Xi_{1}, \bar{w}_{2}+\Xi_{2}, \ldots, \bar{w}_{8}+\Xi_{8}\right)\right]+  \tag{19}\\
+ & \sum_{k \in \mathbb{N}} \bar{z}^{k}\left[-\bar{W}_{k}^{1}\left(\bar{w}_{1}, \bar{w}_{2}, \ldots, \bar{w}_{8}\right)-2 i z \bar{Z}_{k}\left(\bar{w}_{1}, \bar{w}_{2}, \ldots, \bar{w}_{8}\right)\right]
\end{align*}
$$

Then, we expand further each holomorphic function $Z^{k}$ and $W_{k}^{1}$ according to the formulae (cf. (8)):

$$
\begin{gathered}
A\left(\bar{w}_{1}+\Xi_{1}, \bar{w}_{2}+\Xi_{2}, \ldots, \bar{w}_{8}+\Xi_{8}\right)= \\
\sum_{l_{1}, \ldots, l_{8} \in \mathbb{N}} A_{w_{1}^{l_{1}} w_{2}^{l_{2}} \ldots w_{8}^{l_{8}}}\left(\bar{w}_{1}, \bar{w}_{2}, \ldots, \bar{w}_{8}\right) \frac{(2 i z \bar{z})^{l_{1}}}{l_{1}!} \cdot \frac{\left(2 i z^{2} \bar{z}+2 i z \bar{z}^{2}\right)^{l_{2}}}{l_{2}!} \cdot \frac{\left(2 z^{2} \bar{z}-2 z \bar{z}^{2}\right)^{l_{3}}}{l_{3}!} \\
\frac{\left(2 i z^{3} \bar{z}+2 i z \bar{z}^{3}\right)^{l_{4}}}{l_{4}!} \cdot \frac{\left(2 z^{3} \bar{z}+2 z \bar{z}^{3}\right)^{l_{5}}}{l_{5}!} \cdot \frac{\left(2 i z^{2} \bar{z}^{2}\right)^{l_{6}}}{l_{6}!} \\
\frac{\left(2 i z^{4} \bar{z}+2 i z \bar{z}^{4}\right)^{l_{7}}}{l_{7}!} \cdot \frac{\left(2 z^{4} \bar{z}+2 z \bar{z}^{4}\right)^{l_{8}}}{l_{8}!}
\end{gathered}
$$

Chasing the coefficient of $\bar{z}^{k}$ for every $k \geqslant 2$ after further expansion, we therefore see that the first two lines give absolutely no contribution, and that from the third line, it only comes: $0 \equiv \bar{W}_{k}^{1}(\bar{w})$, which is what was claimed about the $W_{k}^{1}$.

Next, chasing the coefficient of $z \bar{z}^{k^{\prime}}$ for every $k^{\prime} \geqslant 6$, we get $0 \equiv \bar{Z}_{k^{\prime}}(\bar{w})$. The seven remaining families of vanishing equations $0 \equiv \bar{W}_{k_{l}}^{l}(\bar{w})$ for $l=2, \ldots, 8$ with $k_{2}, k_{3} \geqslant 3$, with $k_{4}, k_{5} \geqslant 4, k_{6} \geqslant 1$ and with $k_{7}, k_{8} \geqslant 5$ are obtained in a completely similar way by looking at the second to eighth equations of (18).

After this extensive simplification, we try to determine expressions of the remaining 33 holomorphic functions $Z_{0}, Z_{1}, \ldots, W_{4}^{8}$ in the above lemma. Substituting in (18) the already obtained expressions for the nine functions $Z, W^{l}, l=$ $1, \ldots, 8$, the fundamental equations (18) change into the form:
(20)
$0 \equiv \sum_{t=0}^{1}\left(z^{t} W_{t}^{1}(\bar{w}+\Xi)\right)-\sum_{t=0}^{1}\left(\bar{z}^{t} \bar{W}_{t}^{1}(\bar{w})\right)-2 i \sum_{t=0}^{5}\left(z^{t} \bar{z} Z(\bar{w}+\Xi)\right)-2 i \sum_{t=0}^{5}\left(z \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)$,
(21)
$0 \equiv \sum_{t=0}^{2}\left(z^{t} W_{t}^{2}(\bar{w}+\Xi)\right)-\sum_{t=0}^{2}\left(\bar{z}^{t} \bar{W}_{t}^{2}(\bar{w})\right)-4 i \sum_{t=0}^{5}\left(z^{t+1} \bar{z} Z(\bar{w}+\Xi)\right)-$
$-2 i \sum_{t=0}^{5}\left(z^{t} \bar{z}^{2} Z_{t}(\bar{w}+\Xi)\right)-2 i \sum_{t=0}^{5}\left(z^{2} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)-4 i \sum_{t=0}^{5}\left(z \bar{z}^{t+1} \bar{Z}_{t}(\bar{w})\right)$,

> (22)

$$
\begin{aligned}
0 & \equiv \sum_{t=0}^{2}\left(z^{t} W_{t}^{3}(\bar{w}+\Xi)\right)-\sum_{t=0}^{2}\left(\bar{z}^{t} \bar{W}_{t}^{3}(\bar{w})\right)-4 \sum_{t=0}^{5}\left(z^{t+1} \bar{z} Z(\bar{w}+\Xi)\right)+ \\
& +2 \sum_{t=0}^{5}\left(z^{t} \bar{z}^{2} Z_{t}(\bar{w}+\Xi)\right)-2 \sum_{t=0}^{5}\left(z^{2} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)+4 \sum_{t=0}^{5}\left(z \bar{z}^{t+1} \bar{Z}_{t}(\bar{w})\right)
\end{aligned}
$$

$$
\begin{align*}
0 & \equiv \sum_{t=0}^{3}\left(z^{t} W_{t}^{4}(\bar{w}+\Xi)\right)-\sum_{t=0}^{3}\left(\bar{z}^{t} \bar{W}_{t}^{4}(\bar{w})\right)-6 i \sum_{t=0}^{5}\left(z^{t+2} \bar{z} Z(\bar{w}+\Xi)\right)-  \tag{23}\\
& -2 i \sum_{t=0}^{5}\left(z^{t} \bar{z}^{3} Z_{t}(\bar{w}+\Xi)\right)-2 i \sum_{t=0}^{5}\left(z^{3} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)-6 i \sum_{t=0}^{5}\left(z \bar{z}^{t+2} \bar{Z}_{t}(\bar{w})\right),
\end{align*}
$$

$$
\begin{align*}
0 & \equiv \sum_{t=0}^{3}\left(z^{t} W_{t}^{5}(\bar{w}+\Xi)\right)-\sum_{t=0}^{3}\left(\bar{z}^{t} \bar{W}_{t}^{5}(\bar{w})\right)-6 \sum_{t=0}^{5}\left(z^{t+2} \bar{z} Z(\bar{w}+\Xi)\right)+  \tag{24}\\
& +2 \sum_{t=0}^{5}\left(z^{t} \bar{z}^{3} Z_{t}(\bar{w}+\Xi)\right)-2 \sum_{t=0}^{5}\left(z^{3} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)+6 \sum_{t=0}^{5}\left(z \bar{z}^{t+2} \bar{Z}_{t}(\bar{w})\right)
\end{align*}
$$

(25) $0 \equiv W_{0}^{6}(\bar{w}+\Xi)-\bar{W}_{t}^{6}(\bar{w})-4 i \sum_{t=0}^{5}\left(z^{t+1} \bar{z}^{2} Z(\bar{w}+\Xi)\right)-4 i \sum_{t=0}^{5}\left(z^{2} \bar{z}^{t+1} \bar{Z}_{t}(\bar{w})\right)$,
(26)

$$
\begin{aligned}
0 & \equiv \sum_{t=0}^{4}\left(z^{t} W_{t}^{7}(\bar{w}+\Xi)\right)-\sum_{t=0}^{4}\left(\bar{z}^{t} \bar{W}_{t}^{7}(\bar{w})\right)-8 i \sum_{t=0}^{5}\left(z^{t+3} \bar{z} Z(\bar{w}+\Xi)\right)- \\
& -2 i \sum_{t=0}^{5}\left(z^{t} \bar{z}^{4} Z_{t}(\bar{w}+\Xi)\right)-2 i \sum_{t=0}^{5}\left(z^{4} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)-8 i \sum_{t=0}^{5}\left(z \bar{z}^{t+3} \bar{Z}_{t}(\bar{w})\right)
\end{aligned}
$$

> (27)

$$
\begin{aligned}
0 & \equiv \sum_{t=0}^{4}\left(z^{t} W_{t}^{8}(\bar{w}+\Xi)\right)-\sum_{t=0}^{4}\left(\bar{z}^{t} \bar{W}_{t}^{8}(\bar{w})\right)-8 \sum_{t=0}^{5}\left(z^{t+3} \bar{z} Z(\bar{w}+\Xi)\right)+ \\
& +2 \sum_{t=0}^{5}\left(z^{t} \bar{z}^{4} Z_{t}(\bar{w}+\Xi)\right)-2 \sum_{t=0}^{5}\left(z^{4} \bar{z}^{t} \bar{Z}_{t}(\bar{w})\right)+8 \sum_{t=0}^{5}\left(z \bar{z}^{t+3} \bar{Z}_{t}(\bar{w})\right)
\end{aligned}
$$

Now we arrive at the point where we should expand the functions $Z_{\bullet}(\bar{w}+\Xi)$ and $W_{\bullet}^{\bullet}(\bar{w}+\Xi)$ appearing in the above eight equations (20)-(27) using the Taylor series (8). Afterwards, the coefficients of $z^{\mu} \bar{z}^{\nu}$ in these equations should be extracted and set equal to zero, identically. This is equivalent to solve the LinCons PDE system constructed by these coefficients underlying the differential
$\operatorname{ring} R:=\mathbb{C}(w)\left[Z_{\bullet}, W_{\bullet}^{1}, \ldots, W_{\bullet}^{8}\right]$, equipped with the functional conjugation operator.

Doing so, we have extracted these coefficients as much as it was needed ${ }^{4}$ and obtained the following system of 63 equations with 33 unknowns $Z_{0}, Z_{1}, \ldots, W_{4}^{8}$, which are in fact the indeterminates of the differential ring $R$. Here by $(\mu, \nu: \ell)$ we mean the coefficient of $z^{\mu} \bar{z}^{\nu}$ in the fundamental equation $(\ell)$ for $\ell=20, \ldots, 27$ :

> (28)
$(0,1: 20):-2 i Z_{0}-\bar{W}_{1}^{1} \equiv 0, \quad(0,1: 21): \bar{W}_{1}^{2} \equiv 0, \quad(0,1: 22): \bar{W}_{1}^{3} \equiv 0, \quad(0,1: 23): \bar{W}_{1}^{4} \equiv 0$,
$(0,1: 24): \bar{W}_{1}^{5} \equiv 0, \quad(0,1: 25): \bar{W}_{1}^{6} \equiv 0, \quad(0,1: 26): \bar{W}_{1}^{7} \equiv 0, \quad(0,1: 27): \bar{W}_{1}^{8} \equiv 0$,
$(1,1: 20):-2 i Z_{1}-2 i \bar{Z}_{1}+2 i \bar{W}_{0, w^{1}}^{1} \equiv 0, \quad(1,1: 21):-4 i Z_{0}-4 i \bar{Z}_{0}+2 i \bar{W}_{0, w^{1}}^{2} \equiv 0$,
$(1,1: 22):-4 Z_{0}+4 \bar{Z}_{0}+2 i \bar{W}_{0, w^{1}}^{3} \equiv 0, \quad(1,1: 23): W_{0, w^{1}}^{4} \equiv 0, \quad(1,1: 24): W_{0, w^{1}}^{5} \equiv 0$,
$(1,1: 25): W_{0, w^{1}}^{6} \equiv 0, \quad(1,1: 26): W_{0, w^{1}}^{7} \equiv 0, \quad(1,1: 27): W_{0, w^{1}}^{8} \equiv 0$,
$(0,2: 21): 2 i Z_{0}+\bar{W}_{2}^{2} \equiv 0, \quad(0,2: 22): 2 Z_{0}-\bar{W}_{2}^{3} \equiv 0, \quad(0,2: 23): \bar{W}_{2}^{4} \equiv 0$,
$(0,2: 24): \bar{W}_{2}^{5} \equiv 0, \quad(0,2: 26): \bar{W}_{2}^{7} \equiv 0, \quad(0,2: 27): \bar{W}_{2}^{8} \equiv 0$,
$(1,2: 20):-2 i \bar{Z}_{2}+2 i W_{0, w^{2}}^{1}-2 W_{0, w^{3}}^{1}+4 Z_{0, w^{1}} \equiv 0, \quad(1,2: 21):-2 i Z_{1}-4 i \bar{Z}_{1}-2 W_{0, w^{3}}^{2}+2 i W_{0, w^{2}}^{2} \equiv 0$,
$(1,2: 22): 2 Z_{1}+4 \bar{Z}_{1}-2 W_{0, w^{3}}^{3}+2 i W_{0, w^{2}}^{3} \equiv 0, \quad(1,2: 23):-6 i \bar{Z}_{0}-2 W_{0, w^{3}}^{4}+2 i W_{0, w^{2}}^{4} \equiv 0$,
$(1,2: 24): 6 \bar{Z}_{0}-2 W_{0, w^{3}}^{5}+2 i W_{0, w^{2}}^{5} \equiv 0, \quad(1,2: 25):-4 i Z_{0}-2 W_{0, w^{3}}^{6}+2 i W_{0, w^{2}}^{6} \equiv 0$,
$(1,2: 26):-2 W_{0, w^{3}}^{7}+2 i W_{0, w^{2}}^{7} \equiv 0, \quad(1,2: 27):-2 W_{0, w^{3}}^{8}+2 i W_{0, w^{2}}^{8} \equiv 0$,
$(0,3: 23): 2 i Z_{0}+\bar{W}_{3}^{4} \equiv 0, \quad(0,3: 24): 2 Z_{0}-\bar{W}_{3}^{5} \equiv 0, \quad(0,3: 26): \bar{W}_{3}^{7} \equiv 0, \quad(0,3: 27): \bar{W}_{3}^{8} \equiv 0$,
$(1,3: 20):-\bar{W}_{0, w^{5}}^{1}-i \bar{Z}_{3}+i W_{0, w^{4}}^{1} \equiv 0, \quad(1,3: 21):-2 i \bar{Z}_{2}+i W_{0, w^{4}}^{2}-\bar{W}_{0, w^{5}}^{2} \equiv 0$,
$(1,3: 22): 2 \bar{Z}_{2}-W_{0, w^{5}}^{3}+i \bar{W}_{0, w^{4}}^{3} \equiv 0, \quad(1,3: 23):-2 i Z_{1}-6 i \bar{Z}_{1}-2 W_{0, w^{5}}^{4}+2 i \bar{W}_{0, w^{4}}^{4} \equiv 0$,
$(1,3: 24): 2 Z_{1}+6 \bar{Z}_{1}-2 W_{0, w^{5}}^{5}+2 i \bar{W}_{0, w^{4}}^{5} \equiv 0, \quad(1,3: 25):-2 W_{0, w^{5}}^{6}+2 i \bar{W}_{0, w^{4}}^{6} \equiv 0$,
$(1,3: 26):-8 i \bar{Z}_{0}-2 W_{0, w^{5}}^{7}+2 i \bar{W}_{0, w^{4}}^{7} \equiv 0, \quad(1,3: 27): 8 \bar{Z}_{0}-2 W_{0, w^{5}}^{8}+2 i \bar{W}_{0, w^{4}}^{8} \equiv 0$,
$(2,2: 20): i W_{0, w^{6}}^{1}-Z_{1, w^{1}} \equiv 0, \quad(2,2: 21): i W_{0, w^{6}}^{2}-i Z_{2}-i \bar{Z}_{2} \equiv 0$,
$(2,2: 22):-W_{0, w^{6}}^{3}+i Z_{2}-i \bar{Z}_{2} \equiv 0, \quad(2,2: 23): i W_{0, w^{6}}^{4} \equiv 0, \quad(2,2: 24): i W_{0, w^{6}}^{5} \equiv 0$,
$(2,2: 25): i W_{0, w^{6}}^{6}-2 i Z_{1}-2 i \bar{Z}_{1} \equiv 0, \quad(2,2: 26): i W_{0, w^{6}}^{7} \equiv 0, \quad(2,2: 27): i W_{0, w^{6}}^{8} \equiv 0$,
$(0,4: 26): 2 i Z_{0}+\bar{W}_{4}^{7} \equiv 0, \quad(0,4: 27): 2 Z_{0}-\bar{W}_{4}^{8} \equiv 0$,
$(1,4: 20):-i \bar{Z}_{4}+i \bar{W}_{0, w^{7}}^{1}-W_{0, w^{8}}^{1} \equiv 0, \quad(1,4: 21):-2 i \bar{Z}_{3}+i \bar{W}_{0, w^{7}}^{2}-W_{0, w^{8}}^{2} \equiv 0$,
$(1,4: 22): W_{0, w^{8}}^{3}-i W_{0, w^{7}}^{3} \equiv 0, \quad(1,4: 23):-3 i \bar{Z}_{2}+i \bar{W}_{0, w^{7}}^{4}-W_{0, w^{8}}^{4} \equiv 0$,
$(1,4: 24): 3 \bar{Z}_{2}-\bar{W}_{0, w^{8}}^{5}+i W_{0, w^{7}}^{5} \equiv 0, \quad(1,4: 25): 2 i \bar{W}_{0, w^{7}}^{6}-2 i W_{0, w^{8}}^{6} \equiv 0$,
$(1,4: 26):-2 i Z_{1}-8 i \bar{Z}_{1}-2 \bar{W}_{0, w^{8}}^{7}+2 i W_{0, w^{7}}^{7} \equiv 0, \quad(1,4: 27): 2 i Z_{1}+8 \bar{Z}_{1}-2 \bar{W}_{0, w^{8}}^{8}+2 i W_{0, w^{7}}^{8} \equiv 0$,
$(1,4: 21):-i \bar{Z}_{3} \equiv 0, \quad(1,4: 23):-i Z_{2} \equiv 0$,
$(1,5: 20):-i \bar{Z}_{5} \equiv 0, \quad(1,5: 21):-i \bar{Z}_{4} \equiv 0$.

We employ the MAPLE package DifferentialAlgebra, performing the approach described in Section 3 based on the Rosenfeld-Gröbner algorithm to solve

[^2]such a LinCons PDE system, and we obtain the following general solution:
\[

$$
\begin{aligned}
& Z(z, w):=\underbrace{\mathrm{c}+i \mathrm{~d}}_{Z_{0}(w)}+\underbrace{(\mathrm{a}+i \mathrm{~b})}_{Z_{1}(w)} z, \\
& W^{1}(z, w):=\underbrace{\mathrm{c}_{1}+2 \mathrm{a} w^{1}}_{W_{0}^{1}(w)}+2(\underbrace{\mathrm{~d}+i \mathrm{c}}_{W_{1}^{1}(w)}) z, \\
& W^{2}(z, w):=\underbrace{\mathrm{c}_{2}+4 \mathrm{c} w^{1}+3 \mathrm{a} w^{2}-\mathrm{b} w^{3}}_{W_{0}^{2}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{2}^{2}(w)} z^{2}, \\
& W^{3}(z, w):=\underbrace{\mathrm{c}_{3}+4 \mathrm{~d} w^{1}+\mathrm{b} w^{2}+3 \mathrm{a} w^{3}}_{W_{0}^{3}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{2}^{3}(w)} z^{2}, \\
& W^{4}(z, w):=\underbrace{\mathrm{c}_{4}+3 \mathrm{c} w^{2}-3 \mathrm{~d} w^{3}+4 \mathrm{a} w^{4}-2 \mathrm{~b} w^{5}}_{W_{0}^{4}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{3}^{4}(w)} z^{3}, \\
& W^{5}(z, w):=\underbrace{c_{5}+3 \mathrm{~d} w^{2}+3 \mathrm{c} w^{3}+2 \mathrm{~b} w^{4}+4 \mathrm{a} w^{5}}_{W_{0}^{5}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{3}^{5}(w)} z^{3}, \\
& W^{6}(z, w):=\underbrace{\mathrm{c}_{6}+2 \mathrm{c} w^{2}+2 \mathrm{~d} w^{3}+4 \mathrm{a} w^{6}}_{W_{0}^{6}(w)}, \\
& W^{7}(z, w):=\underbrace{c_{7}+4 \mathrm{c} w^{4}-4 \mathrm{~d} w^{5}+5 \mathrm{a} w^{7}-3 \mathrm{~b} w^{8}}_{W_{0}^{7}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{4}^{7}(w)} z^{4}, \\
& W^{8}(z, w):=\underbrace{\mathrm{c}_{8}+4 \mathrm{~d} w^{4}+4 \mathrm{c} w^{5}+3 \mathrm{~b} w^{7}+5 \mathrm{a} w^{8}}_{W_{0}^{8}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{4}^{8}(w)} z^{4},
\end{aligned}
$$
\]

for some twelve real variables $c_{1}, \ldots, c_{8}, a, b, c, d \in \mathbb{R}$. Putting these functions into the general expression $\mathrm{X}:=Z(z, w) \partial_{z}+\sum_{l=1}^{8} W^{l}(z, w) \partial_{w^{l}}$ of the desired infinitesimal CR-automorphisms gives their general form. One can check easily that such a parametrized holomorphic vector field enjoys the tangency condition $\left.(X+\bar{X})\right|_{\mathbb{M}^{1}} \equiv 0$. Picking the coefficients of the above twelve real variables in this general expression, provides twelve $\mathbb{R}$-linearly independent infinitesimal CRautomorphisms $\mathrm{X}_{1}, \ldots, \mathrm{X}_{12}$ which constitute a basis for the desired Lie algebra $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{1}\right)$. Before presenting them, we recall that a Lie algebra $\mathfrak{g}$ is called graded in the sense of Tanaka whenever it admits a gradation like:

$$
\mathfrak{g}:=\mathfrak{g}_{-k} \oplus \cdots \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0} \oplus \mathfrak{g}_{1} \oplus \cdots \oplus \mathfrak{g}_{k^{\prime}}, \quad\left(k, k^{\prime} \in \mathbb{N}\right)
$$

satisfying:

$$
\left[\mathfrak{g}_{i}, \mathfrak{g}_{j}\right] \subset \mathfrak{g}_{i+j}
$$

Theorem 5.1. The Lie algebra of infinitesimal CR-automorphisms $\mathfrak{a u t}_{C R}\left(\mathbb{M}^{1}\right)$ of the rigid real analytic $C R$-generic submanifold $\mathbb{M}^{1} \subset \mathbb{C}^{1+8}$ is 12-dimensional, generated by the twelve $\mathbb{R}$-linearly independent holomorphic vector fields:

$$
\left\{\begin{aligned}
\mathrm{X}_{i} & :=\partial_{w_{i}}, \quad i=1, \ldots, 8 \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}}, \\
\mathrm{X}_{10} & :=i z \partial_{z}-w^{3} \partial_{w^{2}}+w^{2} \partial_{w^{3}}-2 w^{5} \partial_{w^{4}}+2 w^{4} \partial_{w^{5}}-3 w^{8} \partial_{w^{7}}+3 w^{7} \partial_{w^{8}} \\
\mathrm{X}_{11} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(4 w^{4}+2 i z^{4}\right) \partial_{w^{7}}+\left(4 w^{5}+2 z^{4}\right) \partial_{w^{8}} \\
\mathrm{X}_{12} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}+-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+\left(-4 w^{5}+2 z^{4}\right) \partial_{w^{7}}+\left(4 w^{4}-2 i z^{4}\right) \partial_{w^{8}}
\end{aligned}\right.
$$

Furthermore, it is graded of the form:

$$
\mathfrak{a u t}_{C R}\left(\mathbb{M}^{1}\right):=\mathfrak{g}_{-5} \oplus \mathfrak{g}_{-4} \oplus \mathfrak{g}_{-3} \oplus \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}
$$

with $\mathfrak{g}_{-5}:=\left\langle\mathrm{X}_{7}, \mathrm{X}_{8}\right\rangle$, with $\mathfrak{g}_{-4}:=\left\langle\mathrm{X}_{4}, \mathrm{X}_{5}, \mathrm{X}_{6}\right\rangle$, with $\mathfrak{g}_{-3}:=\left\langle\mathrm{X}_{2}, \mathrm{X}_{3}\right\rangle$, with $\mathfrak{g}_{-2}:=\left\langle\mathrm{X}_{1}\right\rangle$, with $\mathfrak{g}_{-1}:=\left\langle\mathrm{X}_{11}, \mathrm{X}_{12}\right\rangle$, and with $\mathfrak{g}_{0}:=\left\langle\mathrm{X}_{9}, \mathrm{X}_{10}\right\rangle$ and together with the following table of commutators:

|  | $\mathrm{X}_{1}$ | $\mathrm{X}_{2}$ | $\mathrm{X}_{3}$ | $\mathrm{X}_{4}$ | $\mathrm{X}_{5}$ | $\mathrm{X}_{6}$ | $\mathrm{X}_{7}$ | $\mathrm{X}_{8}$ | $\mathrm{X}_{9}$ | $\mathrm{X}_{10}$ | $\mathrm{X}_{11}$ | $\mathrm{X}_{12}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{X}_{1}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $2 \mathrm{X}_{1}$ | 0 | $4 \mathrm{X}_{2}$ | $4 \mathrm{X}_{3}$ |
| $\mathrm{X}_{2}$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{2}$ | $\mathrm{X}_{3}$ | $3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ | $3 \mathrm{X}_{5}$ |
| $\mathrm{X}_{3}$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{3}$ | $-\mathrm{X}_{2}$ | $3 \mathrm{X}_{5}$ | $-3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ |
| $\mathrm{X}_{4}$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{4}$ | $2 \mathrm{X}_{5}$ | $4 \mathrm{X}_{7}$ | $4 \mathrm{X}_{8}$ |
| $\mathrm{X}_{5}$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{5}$ | $-2 \mathrm{X}_{4}$ | $4 \mathrm{X}_{8}$ | $-4 \mathrm{X}_{7}$ |
| $\mathrm{X}_{6}$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | $4 \mathrm{X}_{6}$ | 0 | 0 | 0 |
| $\mathrm{X}_{7}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | $5 \mathrm{X}_{7}$ | $3 \mathrm{X}_{8}$ | 0 | 0 |
| $\mathrm{X}_{8}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $5 \mathrm{X}_{8}$ | $-3 \mathrm{X}_{7}$ | 0 | 0 |
| $\mathrm{X}_{9}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | $-\mathrm{X}_{11}$ | $-\mathrm{X}_{12}$ |
| $\mathrm{X}_{10}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $-\mathrm{X}_{12}$ | $\mathrm{X}_{11}$ |
| $\mathrm{X}_{11}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $4 \mathrm{X}_{1}$ |
| $\mathrm{X}_{12}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 |

5.1. Two remaining sought Lie algebras $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{2}\right)$ and $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{3}\right)$. One can perform long computations similar to what we did for $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{1}\right)$ and obtain the structure of the two remaining Lie algebras $\mathfrak{a u t} t_{C R}\left(\mathbb{M}^{2}\right)$ and $\mathfrak{a u t}{ }_{C R}\left(\mathbb{M}^{3}\right)$. Here, we omit the corresponding intermediate computations - since they are similar to those of $\mathbb{M}^{1}$ and offer no new aspect.
Theorem 5.2. The Lie algebra of infinitesimal CR-automorphisms $\mathfrak{a u t} \boldsymbol{u}_{C R}\left(\mathbb{M}^{2}\right)$ of the rigid real analytic generic CR-generic submanifold $\mathbb{M}^{2} \subset \mathbb{C}^{1+8}$, represented as the graph of the eight defining equations:

$$
\begin{aligned}
w^{j}-\bar{w}^{j} & =\Xi_{j}(z, \bar{z}), \quad(j=1 \cdots 6), \\
w^{7}-\bar{w}^{7} & =\Xi_{7}^{\prime}(z, \bar{z}):=2 i\left(z^{3} \bar{z}^{2}+z^{2} \bar{z}^{3}\right), \\
w^{8}-\bar{w}^{8} & =\Xi_{8}^{\prime}(z, \bar{z}):=2\left(z^{3} \bar{z}^{2}-z^{2} \bar{z}^{3}\right),
\end{aligned}
$$

is 12-dimensional with the holomorphic coefficients:

$$
\begin{aligned}
& Z(z, w):=\underbrace{\mathrm{c}+i \mathrm{~d}}_{Z_{0}(w)}+\underbrace{(\mathrm{a}+i \mathrm{~b})}_{Z_{1}(w)} z, \\
& W^{1}(z, w):=\underbrace{\mathrm{c}_{1}+2 \mathrm{a} w^{1}}_{W_{0}^{1}(w)}+2(\underbrace{\mathrm{~d}+i \mathrm{c}}_{W_{1}^{1}(w)}) z, \\
& W^{2}(z, w):=\underbrace{\mathrm{c}_{2}+4 \mathrm{c} w^{1}+3 \mathrm{a} w^{2}-\mathrm{b} w^{3}}_{W_{0}^{2}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{2}^{2}(w)} z^{2}, \\
& W^{3}(z, w):=\underbrace{\mathrm{c}_{3}+4 \mathrm{~d} w^{1}+\mathrm{b} w^{2}+3 \mathrm{a} w^{3}}_{W_{0}^{3}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{2}^{3}(w)} z^{2}, \\
& W^{4}(z, w):=\underbrace{\mathrm{c}_{4}+3 \mathrm{c} w^{2}-3 \mathrm{~d} w^{3}+4 \mathrm{a} w^{4}-2 \mathrm{~b} w^{5}}_{W_{0}^{4}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{3}^{4}(w)} z^{3}, \\
& W^{5}(z, w):=\underbrace{c_{5}+3 \mathrm{~d} w^{2}+3 \mathrm{c} w^{3}+2 \mathrm{~b} w^{4}+4 \mathrm{a} w^{5}}_{W_{0}^{5}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{3}^{5}(w)} z^{3},
\end{aligned}
$$

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$$
\begin{aligned}
& W^{6}(z, w):=\underbrace{\mathrm{c}_{6}+2 \mathrm{c} w^{2}+2 \mathrm{~d} w^{3}+4 \mathrm{a} w^{6}}_{W_{0}^{6}(w)}, \\
& W^{7}(z, w):=\underbrace{\mathrm{c}_{7}+2 \mathrm{c} w^{4}+2 \mathrm{~d} w^{5}+6 \mathrm{c} w^{6}+5 \mathrm{a} w^{7}-\mathrm{b} w^{8}}_{W_{0}^{7}(w)}, \\
& W^{8}(z, w):=\underbrace{\mathrm{c}_{8}-2 \mathrm{~d} w^{4}+2 \mathrm{c} w^{5}+6 \mathrm{~d} w^{6}+\mathrm{b} w^{7}+5 \mathrm{a} w^{8}}_{W_{0}^{8}(w)},
\end{aligned}
$$

and is generated by the twelve $\mathbb{R}$-linearly independent holomorphic vector fields:

$$
\left\{\begin{aligned}
\mathrm{X}_{i}: & :=\partial_{w_{i}}, \quad i=1, \ldots, 8, \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}}, \\
\mathrm{X}_{10} & :=i z \partial_{z}-w^{3} \partial_{w^{2}}+w^{2} \partial_{w^{3}}-2 w^{5} \partial_{w^{4}}+2 w^{4} \partial_{w^{5}}-w^{8} \partial_{w^{7}}+w^{7} \partial_{w^{8}}, \\
\mathrm{X}_{11} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(2 w^{4}+6 w^{6}\right) \partial_{w^{7}}+2 w^{5} \partial_{w^{8}}, \\
\mathrm{X}_{12} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+2 w^{5} \partial_{w^{7}}+\left(-2 w^{4}+6 w^{6}\right) \partial_{w^{8}} .
\end{aligned}\right.
$$

Furthermore, it is graded of the form:

$$
\mathfrak{a u t}_{C R}\left(\mathbb{M}^{1}\right):=\mathfrak{g}_{-5} \oplus \mathfrak{g}_{-4} \oplus \mathfrak{g}_{-3} \oplus \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}
$$

with $\mathfrak{g}_{-5}:=\left\langle\mathrm{X}_{7}, \mathrm{X}_{8}\right\rangle$, with $\mathfrak{g}_{-4}:=\left\langle\mathrm{X}_{4}, \mathrm{X}_{5}, \mathrm{X}_{6}\right\rangle$, with $\mathfrak{g}_{-3}:=\left\langle\mathrm{X}_{2}, \mathrm{X}_{3}\right\rangle$, with $\mathfrak{g}_{-2}:=\left\langle\mathrm{X}_{1}\right\rangle$, with $\mathfrak{g}_{-1}:=\left\langle\mathrm{X}_{11}, \mathrm{X}_{12}\right\rangle$, and with $\mathfrak{g}_{0}:=\left\langle\mathrm{X}_{9}, \mathrm{X}_{10}\right\rangle$ and together with the following table of commutators:

|  | $\mathrm{X}_{1}$ | $\mathrm{X}_{2}$ | $\mathrm{X}_{3}$ | $\mathrm{X}_{4}$ | $\mathrm{X}_{5}$ | $\mathrm{X}_{6}$ | $\mathrm{X}_{7}$ | $\mathrm{X}_{8}$ | $\mathrm{X}_{9}$ | $\mathrm{X}_{10}$ | $\mathrm{X}_{11}$ | $\mathrm{X}_{12}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{X}_{1}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $2 \mathrm{X}_{1}$ | 0 | $4 \mathrm{X}_{2}$ | $4 \mathrm{X}_{3}$ |
| $\mathrm{X}_{2}$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{2}$ | $\mathrm{X}_{3}$ | $3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ | $3 \mathrm{X}_{5}$ |
| $\mathrm{X}_{3}$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{3}$ | $-\mathrm{X}_{2}$ | $3 \mathrm{X}_{5}$ | $-3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ |
| $\mathrm{X}_{4}$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{4}$ | $2 \mathrm{X}_{5}$ | $2 \mathrm{X}_{7}$ | $-2 \mathrm{X}_{8}$ |
| $\mathrm{X}_{5}$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{5}$ | $-2 \mathrm{X}_{4}$ | $2 \mathrm{X}_{8}$ | $2 \mathrm{X}_{7}$ |
| $\mathrm{X}_{6}$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | $4 \mathrm{X}_{6}$ | 0 | $6 \mathrm{X}_{7}$ | 0 |
| $\mathrm{X}_{7}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | $5 \mathrm{X}_{7}$ | $\mathrm{X}_{8}$ | 0 | 0 |
| $\mathrm{X}_{8}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $5 \mathrm{X}_{8}$ | $-\mathrm{X}_{7}$ | 0 | 0 |
| $\mathrm{X}_{9}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | $-\mathrm{X}_{11}$ | $-\mathrm{X}_{12}$ |
| $\mathrm{X}_{10}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $-\mathrm{X}_{12}$ | $\mathrm{X}_{11}$ |
| $\mathrm{X}_{11}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $4 \mathrm{X}_{1}$ |
| $\mathrm{X}_{12}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 |

Theorem 5.3. The Lie algebra of infinitesimal CR-automorphisms $\mathfrak{a u t} \mathrm{u}_{C R}\left(\mathbb{M}^{3}\right)$ of the rigid real analytic CR-generic submanifold $\mathbb{M}^{3} \subset \mathbb{M}^{1+8}$, represented as the graph of the eight defining equations:

$$
\begin{aligned}
w^{j}-\bar{w}^{j} & =\Xi_{j}(z, \bar{z}), \quad(j=1 \cdots 6), \\
w^{7}-\bar{w}^{7} & =\Xi_{7}^{\prime}(z, \bar{z}), \\
w^{8}-\bar{w}^{8} & =\Xi_{8}^{\prime \prime}(z, \bar{z}):=2 i\left(z^{4} \bar{z}+z \bar{z}^{4}\right),
\end{aligned}
$$

is 11-dimensional with the coefficients:

$$
\begin{aligned}
Z(z, w) & :=\underbrace{\mathrm{c}+i \mathrm{~d}}_{Z_{0}(w)}+\underbrace{\mathrm{a}}_{Z_{1}(w)} z, \\
W^{1}(z, w) & :=\underbrace{c_{1}+2 \mathrm{a} w^{1}}_{W_{0}^{1}(w)}+2(\underbrace{\mathrm{~d}+i \mathrm{c})}_{W_{1}^{1}(w)} z, \\
W^{2}(z, w) & :=\underbrace{\mathrm{c}_{2}+4 \mathrm{c} w^{1}+3 \mathrm{a} w^{2}}_{W_{0}^{2}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{2}^{2}(w)} z^{2}, \\
W^{3}(z, w) & :=\underbrace{\mathrm{c}_{3}+4 \mathrm{~d} w^{1}+3 \mathrm{a} w^{3}}_{W_{0}^{3}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{2}^{3}(w)} z^{2}, \\
W^{4}(z, w) & :=\underbrace{\mathrm{c}_{4}+3 \mathrm{c} w^{2}-3 \mathrm{~d} w^{3}+4 \mathrm{a} w^{4}}_{W_{0}^{4}(w)}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{3}^{4}(w)} z^{3}, \\
W^{5}(z, w) & :=\underbrace{c_{5}+3 \mathrm{~d} w^{2}+3 \mathrm{c} w^{3}+4 \mathrm{a} w^{5}}_{W_{0}^{5}(w)}+\underbrace{2(\mathrm{c}-i \mathrm{~d})}_{W_{3}^{5}(w)} z^{3}, \\
W^{6}(z, w) & :=\underbrace{c_{6}+2 \mathrm{c} w^{2}+2 \mathrm{~d} w^{3}+4 \mathrm{a} w^{6}}_{W_{0}^{6}(w)}, \\
W^{7}(z, w) & :=\underbrace{\mathrm{c}_{7}+2 \mathrm{c} w^{4}+2 \mathrm{~d} w^{5}+6 \mathrm{c} w^{6}}_{W_{0}^{7}(w)}+5 \mathrm{a} w^{7},
\end{aligned} W_{W_{0}^{8}(w)}^{W^{8}(z, w)}:=\underbrace{\mathrm{c}^{8}}_{\mathrm{c}_{8}+4 \mathrm{c} w^{4}-4 \mathrm{~d} w^{5}+5 \mathrm{a} w^{8}}+\underbrace{2(\mathrm{~d}+i \mathrm{c})}_{W_{4}^{8}(w)} z^{4},,
$$

and is generated by the eleven $\mathbb{R}$-linearly independent holomorphic vector fields:

$$
\left\{\begin{aligned}
\mathrm{X}_{i} & :=\partial_{w_{i}}, \quad i=1, \ldots, 8 \\
\mathrm{X}_{9} & :=z \partial_{z}+2 w^{1} \partial_{w^{1}}+3 w^{2} \partial_{w^{2}}+3 w^{3} \partial_{w^{3}}+4 w^{4} \partial_{w^{4}}+ \\
& +4 w^{5} \partial_{w^{5}}+4 w^{6} \partial_{w^{6}}+5 w^{7} \partial_{w^{7}}+5 w^{8} \partial_{w^{8}}, \\
\mathrm{X}_{10} & :=\partial_{z}+2 i z \partial_{w^{1}}+\left(4 w^{1}+2 i z^{2}\right) \partial_{w^{2}}+2 z^{2} \partial_{w^{3}}+\left(3 w^{2}+2 i z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{3}+2 z^{3}\right) \partial_{w^{5}}+2 w^{2} \partial_{w^{6}}+\left(2 w^{4}+6 w^{6}\right) \partial_{w^{7}}+\left(4 w^{4}+2 i z^{4}\right) \partial_{w^{8}}, \\
\mathrm{X}_{11} & :=i \partial_{z}+2 z \partial_{w^{1}}+2 z^{2} \partial_{w^{2}}+\left(4 w^{1}-2 i z^{2}\right) \partial_{w^{3}}+\left(-3 w^{3}+2 z^{3}\right) \partial_{w^{4}}+ \\
& +\left(3 w^{2}-2 i z^{3}\right) \partial_{w^{5}}+2 w^{3} \partial_{w^{6}}+2 w^{5} \partial_{w^{7}}+\left(-4 w^{5}+2 z^{4}\right) \partial_{w^{8}}
\end{aligned}\right.
$$

## Furthermore, it is graded of the form:

$$
\mathfrak{a u t}_{C R}\left(\mathbb{M}^{1}\right):=\mathfrak{g}_{-5} \oplus \mathfrak{g}_{-4} \oplus \mathfrak{g}_{-3} \oplus \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}
$$

with $\mathfrak{g}_{-5}:=\left\langle\mathrm{X}_{7}, \mathrm{X}_{8}\right\rangle$, with $\mathfrak{g}_{-4}:=\left\langle\mathrm{X}_{4}, \mathrm{X}_{5}, \mathrm{X}_{6}\right\rangle$, with $\mathfrak{g}_{-3}:=\left\langle\mathrm{X}_{2}, \mathrm{X}_{3}\right\rangle$, with $\mathfrak{g}_{-2}:=\left\langle\mathrm{X}_{1}\right\rangle$, with $\mathfrak{g}_{-1}:=\left\langle\mathrm{X}_{10}, \mathrm{X}_{11}\right\rangle$, and with $\mathfrak{g}_{0}:=\left\langle\mathrm{X}_{9}\right\rangle$ and together with the following table of commutators:

|  | $\mathrm{X}_{1}$ | $\mathrm{X}_{2}$ | $\mathrm{X}_{3}$ | $\mathrm{X}_{4}$ | $\mathrm{X}_{5}$ | $\mathrm{X}_{6}$ | $\mathrm{X}_{7}$ | $\mathrm{X}_{8}$ | $\mathrm{X}_{9}$ | $\mathrm{X}_{10}$ | $\mathrm{X}_{11}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{X}_{1}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $2 \mathrm{X}_{1}$ | $4 \mathrm{X}_{2}$ | $4 \mathrm{X}_{3}$ |
| $\mathrm{X}_{2}$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{2}$ | $3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ | $3 \mathrm{X}_{5}$ |
| $\mathrm{X}_{3}$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | 0 | $3 \mathrm{X}_{3}$ | $3 \mathrm{X}_{5}$ | $-3 \mathrm{X}_{4}+2 \mathrm{X}_{6}$ |
| $\mathrm{X}_{4}$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{4}$ | $2 \mathrm{X}_{7}+4 \mathrm{X}_{8}$ | 0 |
| $\mathrm{X}_{5}$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | 0 | $4 \mathrm{X}_{5}$ | 0 | $2 \mathrm{X}_{7}-4 \mathrm{X}_{8}$ |
| $\mathrm{X}_{6}$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | 0 | $4 \mathrm{X}_{6}$ | $6 \mathrm{X}_{7}$ | 0 |
| $\mathrm{X}_{7}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | 0 | $5 \mathrm{X}_{7}$ | 0 | 0 |
| $\mathrm{X}_{8}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $5 \mathrm{X}_{8}$ | 0 | 0 |
| $\mathrm{X}_{9}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $-\mathrm{X}_{10}$ | $-\mathrm{X}_{11}$ |
| $\mathrm{X}_{10}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 | $4 \mathrm{X}_{1}$ |
| $\mathrm{X}_{11}$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | $*$ | 0 |

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[^0]:    ${ }^{1}$ Not every linear differential polynomial is a LinCons one, in general. For example, as an element of $\mathbb{C}(x, y)[u, v]$, the polynomial $p:=x^{2} y u_{x}+2 y v_{x y}$ is linear while its coefficients are not constant.

[^1]:    ${ }^{2}$ One should notice that since the base field contains $\mathbb{Q}$, then the radical of a differential ideal is a radical differential ideal (cf. [29], Proposition 2.1).
    ${ }^{3}$ For more details on this package, we refer to http://www.maplesoft.com/support/help

[^2]:    ${ }^{4}$ The number of the equations that we found during this step was more than 63 but many of them could be obtained from the remaining ones.

