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1 Flow and transport in the vadose zone: On the impact of partial
2 saturation and Peclet number on non-Fickian, pre-asymptotic
3 dispersion

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8 **Abstract**

9 Transport phenomena in unsaturated porous media still present an important research topic.
10 In particular, in the context of recent environmental concerns, further understanding of
11 contaminant transport in the partially saturated vadose zone is necessary. However, there is
12 currently a lack of understanding of the relationship between water saturation, in particular
13 the two-phase distribution, and dispersion. This is due to the intricate interactions between
14 the two-phase flow and the porous structure, as well as the complexity of the experimental
15 techniques, which prevents a significant number of configurations from being analysed.

16 We explore passive tracer transport in two-dimensional unsaturated porous media via
17 experimental and numerical methods. To this goal, we conduct co-injection experiments to
18 produce two-phase distributions (air/water) at different saturations in a transparent micro-
19 model that mimics the topology of the Bentheimer sandstone. From these experiments, we
20 generate images using multi-scale multiple-point statistics modeling (MPS). Employing the
21 Lattice Boltzmann method, we calculate velocity and concentration fields for both experi-
22 mental and generated images under saturated and unsaturated conditions. Our results show
23 strong similarities in velocity distributions, good agreement in concentration profiles, and
24 a matching of dispersion characteristics between experimental and MPS-generated images.
25 MPS enables us to create a variety of unsaturated porous media structures with different
26 topologies but similar transport properties. From these images, we analyse transport over
27 a large range of saturations and Peclet numbers. We observe pre-asymptotic non-Fickian
28 transport regimes characterised by a variance increasing with time according to a power law
29 with exponent $\alpha > 1$. We find that α increases as saturation decreases, due to enhanced
30 flow heterogeneity, and with higher Peclet numbers. This behavior is confirmed through
31 large-scale simulations.

32 *Keywords:* Anomalous transport, Dispersion, Unsaturated porous media, Lattice
33 Boltzmann

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34 **Nomenclature**

ϕ	Porosity
θ	Water content
S_w	Water saturation
τ	Tortuosity
k	Permeability
k_r	Relative permeability
L_x	Length of the micromodel
L_y	Width of the micromodel
L_z	Depth of the micromodel
Pe	Peclet number
ν	Fluid kinematic viscosity
ρ	Fluid density
P	Pressure
\mathbf{u}	Local velocity field
σ_u	Normalized standard deviation of the velocity field

35 **1. Introduction**

36 Human activity influences largely the subsurface, and particularly the unsaturated vadose
 37 zone. This part of Earth located below the land surface and just above the water tables is
 38 most of the time only partially saturated with water. It plays a key role in hydrogeology,
 39 as the refilling of aquifers usually takes place in this part of the subsurface. The vadose
 40 zone can be impacted by pollution, coming from agriculture or industrial activities, which
 41 impairs the water resources. Furthermore, the water saturation level may vary, notably
 42 during periods of droughts or heavy rainfall. Therefore, it is crucial to be able to predict
 43 contaminant transport for various saturation conditions in the vadose zone. In contrast to
 44 unsaturated media, transport in heterogeneous, saturated porous media has been the subject
 45 of numerous studies, e.g reviewed in [1, 2]. However, dispersion in unsaturated porous media
 46 still remains a significant research topic, notably because of the complex multiphase flow
 47 interactions with the porous structure, which are not yet fully understood.

48 The difficulty lies in the fact that the volume of pores accessible to pollutants depends
 49 on the interaction of the non-miscible air/water flow with the porous medium. Indeed, the
 50 presence of air clusters induces a greater flow heterogeneity. As a result, the velocity field
 51 presents stagnant zones with very low velocities as well as preferential paths with high ve-
 52 locities [3, 4, 5]. Flow, and consequently transport, will thus depend on both the saturation
 53 and the medium heterogeneity. In stagnant zones, transport is controlled by diffusion and
 54 is, therefore, very slow. Transport in the preferential paths, however, is mainly advective
 55 and much faster, leading to extreme solute displacements [6]. As a result, dispersion in un-
 56 saturated porous media is far more complex than in saturated ones. Further comprehension

57 on the joint influence of the pore topology and the two-phase non-miscible air/water distri-
58 bution on the macroscopic transport is crucial to fully understand dispersion phenomena in
59 the unsaturated subsurface.

60 A large number of experiments have been performed to determine the dispersion coeffi-
61 cient or the dispersivity in porous structures at various saturations. However, authors have
62 different points of view on the influence of saturation on dispersion. Many authors note
63 an increase of dispersion/dispersivity in unsaturated porous media, compared to saturated
64 conditions (e.g. [7, 8, 9, 10]), related to an increase in heterogeneity. In contrast, other
65 works highlight non monotonic relations between the saturation and the dispersivity, or the
66 dispersion coefficient [11, 12, 13]. Few other articles show different tendencies from those
67 mentioned above (e.g. [14, 15]). These discrepancies could be explained by the limited num-
68 ber of experiments, which leads to statistical incoherence; and by the different experimental
69 approaches and different ways of interpreting the data.

70 The determination of a constant dispersion coefficient also assumes that transport is
71 Fickian, i.e. governed by a advection-diffusion equation (ADE). It is worth mentioning that
72 Fickian regime is very frequently observed. Indeed, the central limit theorem states that
73 transport becomes Fickian in an asymptotic regime if the variance of the displacement is
74 finite. However, it has been shown that a Fickian transport model often fails to predict
75 dispersion in unsaturated porous media [7, 16, 17, 18, 6, 19]. A key feature of Fickian
76 transport is the linear growth of the second moment of the concentration field over time.
77 Thus, the most convenient way to determine the Fickian nature of the transport is to analyse
78 the time evolution of the second moment. Often non-Fickian behaviour is characterised by
79 a power law time evolution of this moment, referred to as 'anomalous' dispersion [20, 16,
80 17, 21]. The main objective of this paper is therefore to assess and quantify the nature of
81 transport in unsaturated porous media by analysing the temporal evolution of the second
82 spatial moment.

83 The effect of saturation on dispersion has been the subject of numerous studies. In
84 particular, three-dimensional column experiments are often used to study dispersion in un-
85 saturated sand, rock or soil samples (e.g. [8, 10, 11, 9, 7]). In such configurations, due to
86 the opacity of the samples, transport is often analysed using breakthrough curves (average
87 concentration at the outlet). Dispersion in unsaturated porous media can also be studied
88 by means of transparent micromodels. Indeed, micromodels allow direct visualization of the
89 solid structure, two-phase distribution and concentration pattern. Dispersion is then deter-
90 mined from the spatial moments of the concentration profiles as well as the breakthrough
91 curves [7, 6, 5, 4].

92 The first step in assessing the influence of saturation on the dispersion is to understand
93 the spatial distribution of the immiscible phases. A simple way to generate realistic unsatu-
94 rated porous media is to co-inject the two immiscible phases. Immiscible multiphase flow pro-
95 cesses have been extensively studied using micromodel experiments (e.g. [22, 23, 24, 25, 26?
96]). Multiphase configurations mainly depend on the capillary number, on the saturation of
97 each phase and on the flow history [24]. Many tracer experiments have been performed in
98 micromodels in either saturated (e.g. [27, 28, 29]) or unsaturated (e.g. [30, 31, 12, 6, 5, 4, 32])
99 conditions. However, transport experiments in micromodels are limited by several aspects.

100 As dispersion tends to increase in unsaturated conditions, the micromodel size may not al-
101 ways be appropriate. Furthermore, as saturation decreases with flow rate, it is difficult to
102 investigate a wide range of Peclet numbers (ratio of advection time to diffusion time) for a
103 given saturation. In addition, as discussed in [5, 33], it is difficult to experimentally obtain
104 neat tracer injection conditions due to the dispersion in the inlet tubing. Consequently, the
105 experimental uncertainties compromise the analysis of the nature of dispersion.

106 To overcome these difficulties, several authors have used numerical simulations. The
107 critical factor for these simulations is to ensure an accurate representation of the immisci-
108 ble phase distribution. Images can be obtained either experimentally or numerically (from
109 two-phase flow simulations or machine learning methods) [34, 4, 19, 17]. The main disad-
110 vantage of numerical simulations is the high computational cost of solving the two-phase
111 flow equations.

112 However, numerical simulations allow a more accurate resolution of the transport equa-
113 tion with a neat inlet condition, a wider range of Peclet number and are less limited in size
114 than experiments. Highly parallelizable Lattice Boltzmann simulations are commonly used
115 to simulate flow and transport in complex porous media [35, 36, 37].

116 Further understanding of the coupling between pore structure, immiscible phase distribu-
117 tion and transport requires a statistically relevant amount of data. Indeed, as the saturation
118 decreases, heterogeneity becomes more important, as the air cluster size distribution widens.

119 To address this augmented heterogeneity, one can either increase the sample size or
120 the number of configurations with identical statistical properties. Jiménez-Martínez *et al.*
121 [4] considered a machine learning approach based on multiple-point statistical simulations
122 (MPS) [38] to generate two-phase distributions in a given two-dimensional porous struc-
123 ture consisting of irregularly arranged spheres. The MPS approach, initially developed for
124 geological modeling, makes it possible to generate images with complex features that are
125 derived from a reference image, referred to as the Training Image (TI) and representing the
126 expected structure. In this work, we extend the machine learning approach considered by
127 Jiménez-Martínez *et al.*. However, unlike Jiménez-Martínez *et al.* who only generate the
128 air-water distribution for a given solid configuration, we use an MPS algorithm to generate
129 both different solid and water/air configurations. The training images represent two fluid-
130 phase distributions (air/water) in porous media obtained experimentally, when a steady
131 state is reached and air clusters are immobile. By this approach, the coupling between
132 saturation and pore topology can be easily studied for different structures. Moreover, this
133 method allows a significant statistical analysis.

134 The article is structured as follows: we begin by presenting experiments on two-phase
135 flow in a micromodel that represents a 2D natural rock formation. These experiments
136 enable the acquisition of a training image database for different phase configurations. In
137 the following section, we introduce the MPS algorithm used to generate the image database
138 with various configurations and different saturations. Then, we will introduce the Lattice
139 Boltzmann simulations performed to solve flow and transport in these images. Finally, we
140 analyse the distribution of air and water in the porous medium as well as the dispersion,
141 Fickian or non-Fickian, depending on the saturation and Peclet number.

142 2. Experimental and numerical methods

143 In the following, we briefly present the experimental and numerical methods developed
144 and their validation. Further details can be found in the Supplementary Information.

145 2.1. Multiphase flow in a micromodel

146 This section provides an overview of the experiment conducted in an irregular porous
147 glass micromodel to obtain air/water distributions at different saturations. To this end, we
148 apply co-injection of air and water. We performed experiments at various fractional flow
149 rates in order to obtain images at different saturations. We hereby present the micromodel
150 structure and the experimental setup.

151 2.1.1. Experimental setup

152 *Micromodel.* We use a glass micromodel with an inner etched irregular network. The dimen-
153 sions of the micromodel are $L_y = 10mm$ wide by $L_x = 17mm$ long. The model is wet-etched
154 with depth of $L_z = 40\mu m$. The interior model network is based on an image of a 2D slice
155 of Bentheimer sandstone rock, obtained from X-Ray tomography. It was modified to ensure
156 percolation in 2D leading to a final porosity higher than the one of the original rock. The
157 micromodel is presented in Fig. 1a. The porous medium is characterised by a total number
158 of 2600 grains. The average porosity of the micromodel is $\phi = 66\%$ and the permeability
159 including inlet and outlet tubings is 4.7 Darcy (taken from [39]). The micromodel can be
160 considered as strongly water wetting as it is made of glass.

161 *Microfluidic set-up.* The micromodel is connected to a Vinduum pump (delivering a contin-
162 uous flow rate) at lateral inlets for water injection and to a Harvard syringe pump at the
163 center inlet for gas injection. The outlet is connected to the pressure and flow rate sensors.
164 The gas used is ambient air and the liquid is MilliQ water. We used Parker Quink ink
165 as tracer. The value of the diffusion coefficient at our experimental conditions is around
166 $2.710^{-8}mm^2.s^{-1}$ following the measurement of [40]. The micromodel is inserted in a holder
167 and placed horizontally on the optical bench (avoiding gravity effects), above a flat dome
168 red light with adjustable intensity. A high speed camera with a lens is placed above the
169 system to visualize the air-water distributions. The camera JAI (SP-12000M-CXP4 model)
170 provides a 12-megapixel monochrome resolution (4096×3072 pixel), the full-field framerate
171 is 189 frames per second (fps). The acquisition is performed by the Hiris software. The ex-
172 perimental setup is presented in Fig. 1b. The pressure drop of the water phase is measured
173 to determine the permeability of the system. The room temperature was regulated at $21^\circ C$.

174 *Co-injection experiments.* The objective of the experimental part is to obtain a homogeneous
175 distribution of trapped air clusters in the micromodel at different water saturations. To
176 this goal, we chose to inject air and water simultaneously in the micromodel at different
177 fractional flow rates, resulting in uniform distributions of the air and the water phase in the
178 micromodel. Modifying the fractional flow rate between air and water results in different
179 water saturations at steady state. The flow rates were in the range of $0.1\mu L.min^{-1}$ and
180 $1mL.min^{-1}$. Co-injection is not maintained over a long period of time but is stopped

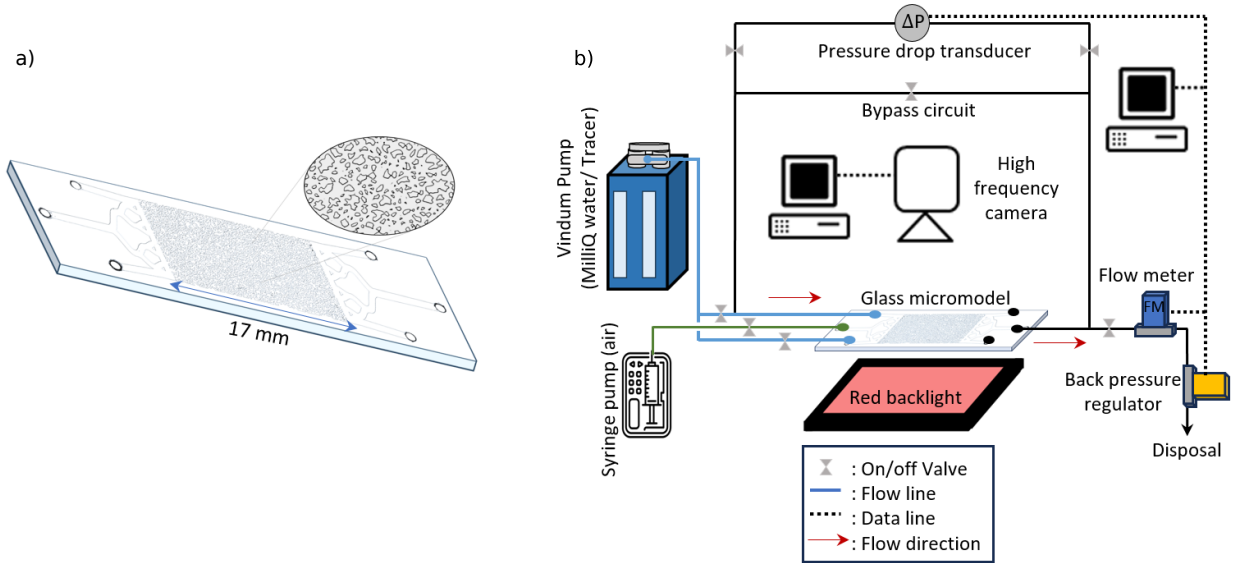


Figure 1: a) Micromodel, b) Experimental setup

181 once the air distribution reaches a steady state after several seconds. Then we perform the
 182 transport experiment. Please note that similar experimental protocols were used for example
 183 in [23, 24, 41, 42] providing a deeper analysis of the two-phase distribution resulting from a
 184 co-injection procedure.

185 *Image processing.* The solid, air and water phases are distinguished through segmentation
 186 of the images using a thresholding technique. Each phase is then associated to a specific
 187 grey level. Fig. 2 shows the original two-phase distribution in the micromodel a) and the
 188 segmented image b). Further details on the image segmentation can be found in the Sup-
 189 plemental Information (SI). The segmented image is analysed using the ImageJ Analyse
 190 Particles tool to obtain structure properties: grain and air cluster size as well as shape char-
 191 acteristics. Pore size distribution is computed using ImageJ plugin for Watershed separation
 192 on the binarized porous structure.

193 2.1.2. Characterization of non-Fickian dispersion with spatial moments

194 Fractional dispersion has been introduced to describe anomalous dispersion where the
 195 spatial and/or temporal moments vary according to a power law (e.g. [43, 44]). For example,
 196 it can be associated with random walk models such as the Levy walk and Levy flights, which
 197 are characterised by broad distributions of temporal or spatial random steps [45, 46, 47].

198 To characterise non-Fickian dispersion, we determine the temporal evolution of the sec-
 199 ond spatial moment (see Supplemental Information). We then fit the second moment with
 200 a power law with exponent α and a fractional dispersion coefficient D_{α}^{frac} :

$$\sigma_{fit}^2 = D_{\alpha}^{frac} t^{\alpha}. \quad (1)$$

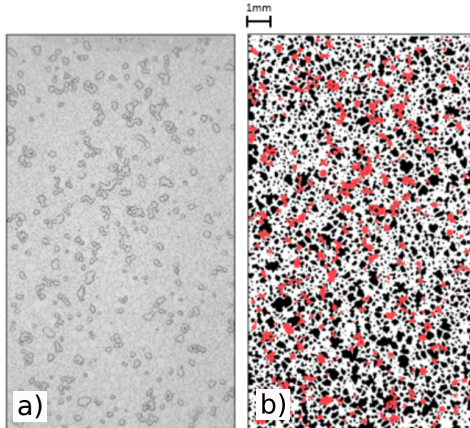


Figure 2: Phase segmentation: a) Raw experimental image with air clusters and water. b) Processed image after phase segmentation, air (red), solid (black), water (white).

201 The coefficient α characterises the nature of dispersion. If α is close to 1, dispersion is Fick-
 202 ian, it is non-Fickian otherwise. D_α^{frac} quantifies the magnitude of the dispersion (Fickian or
 203 not). However, it is worth noting that comparing different values of D_α^{frac} is meaningless as
 204 soon as α is different. For this reason, when comparing the evolution of D_α^{frac} for different
 205 parameters (Peclet number Pe , S), we are led to impose α .

206 2.2. Flow and transport equations

207 We treat the non-wetting phase as immobile because we assume that the flow rate for
 208 the tracer experiment is small enough not to displace the gas. Considering higher flow rates
 209 would require the use of a two-phase flow solver, which has a much higher computational
 210 cost. Consequently, we treat the gas as solid and consider flow and transport only in the
 211 water phase. In the following, we first detail the flow and transport equations solved in
 212 order to obtain the velocity and concentration field for each configuration. We then briefly
 213 present the numerical method used for the resolution of the equations. Finally, we present
 214 a comparison between experimental and numerical data.

215 *Flow equation.* The local velocity field \mathbf{u} in the fluid phase is computed by solving the
 216 Darcy-Brinkman equation [48]:

$$-\frac{\rho\nu}{k}\mathbf{u} - \nabla P + \rho\nu\nabla^2\mathbf{u} = \mathbf{0}, \quad (2)$$

217 where ρ is the density of the fluid, ν represents the kinematic viscosity and P is the pressure.

218 The Darcy-Brinkman equation is used to compute the depth-average velocity. This allows
 219 to describe a 3D velocity field with a 2D equation as demonstrated by [49]. The permeability
 220 k can be computed from the depth as $k = L_z^2/12$. Physically, the Laplacian term models
 221 the transverse diffusion of momentum. It can be used, for example, to describe the boundary
 222 layer introduced by the no-slip condition at the wall. In principle, the viscosity in front of
 223 the Laplacian should be slightly different from that in the Darcy term [49]. However, in

224 our case the permeability is so low that the boundary layer is very small and therefore has
 225 almost no effect on the dispersion [50, 51]. For simplicity, we have chosen to assume that
 226 the two viscosities are equal. And for the same reason, we assume a no-slip condition at the
 227 air-water interface.

228 *Advection-Diffusion-Equation.* Transport is simulated by solving the local advection-diffusion
 229 equation given by

$$\frac{\partial c}{\partial t} + \mathbf{u} \cdot \nabla c - D_m \Delta c = 0, \quad (3)$$

230 where c is the solute concentration in the fluid, \mathbf{u} the local velocity vector obtained from
 231 the resolution of the Darcy-Brinkman equation and D_m the molecular diffusion coefficient.
 232 Similar to previous work, [4], we use a constant diffusion coefficient here. We note however
 233 that because the flow profile is not homogeneous in the depth, one should expect that the
 234 local flow velocity increases the local dispersion coefficient (Taylor dispersion). By neglecting
 235 this effect, we thus assume that the molecular diffusion is dominant over advection at the
 236 scale of the gap depth (see also [51]). Indeed, the Peclet number defined with the depth is
 237 lower than the one defined using the pore diameter.

238 *Lattice Boltzmann simulations.* Two-Relaxation-Time Lattice (TRT) Boltzmann simula-
 239 tions were used to solve Eq. (2) and Eq. (3) to obtain the flow and concentration field
 240 in the porous structures. Details on Lattice Boltzmann schemes for the resolution of Eqs.
 241 (2) and (3) and the applied boundary conditions are provided in the Supplemental Infor-
 242 mation file or can be found in [52, 53]. Parameters chosen for the simulation can also be
 243 found in the Supplemental Information file. LB computations were performed by adapting
 244 the open framework software Walberla [54, 55].

245 2.3. Comparison of experiments and simulations

246 We consider continuous tracer injection starting at a specific time $t = 0$, where molecules
 247 are injected at the inlet. Fig. 3 shows an image of the micromodel with the three phases
 248 (water, air, solid), the porous structure on which simulations are performed (supposing that
 249 the gas behaves as the solid), the velocity field in the fluid phase and the concentration field.

250
 251 We evaluate the influence of these simulation assumptions on transport and the suitability
 252 of the method for studying transport in unsaturated micromodels. This is achieved by
 253 performing a comparative analysis between the experimental work and Lattice Boltzmann
 254 simulations for three different saturations as shown in Fig. 4. Since the numerical and
 255 experimental injection conditions are not the same, the comparison requires to shift the
 256 origin of time and position. Notably, as the front is more dispersed in the experiments,
 257 a position relative to the real position in the experimental case is defined with an offset
 258 subtracted to compensate for the spreading at the inlet. Qualitative agreement is then
 259 observed, in particular the preferential paths and stagnant, dead end zones are fairly well
 260 reproduced. To be more quantitative, we plot the experimental and numerical concentration
 261 profiles (see Fig. 5a-c) at different time. As can be seen, there is an agreement between

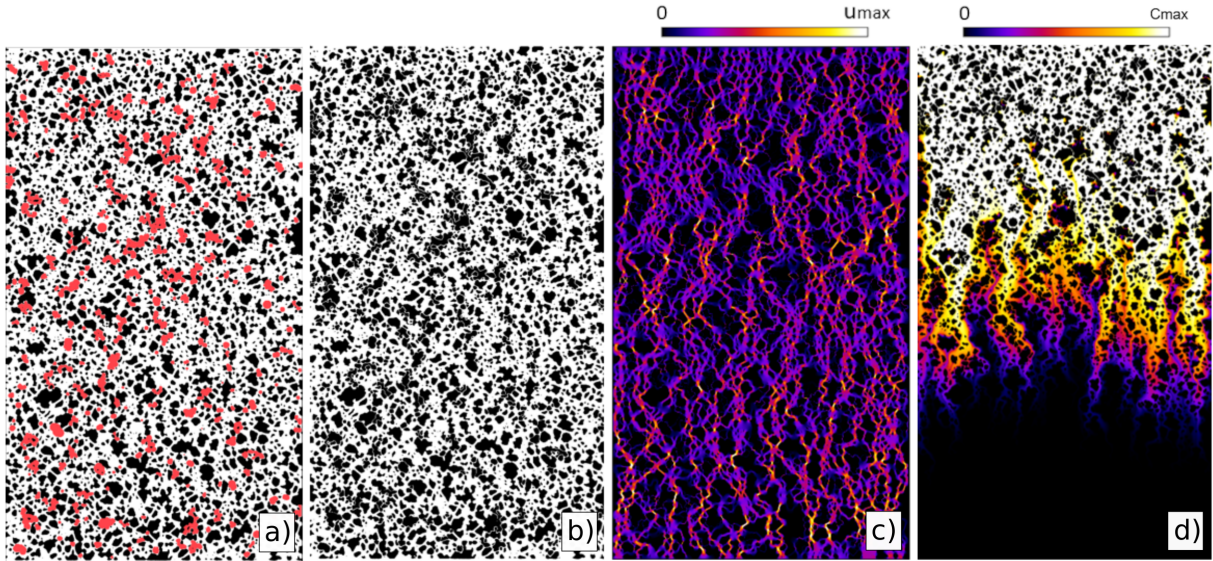


Figure 3: a) Segmented image, air (red), solid (black), water (white). b) Binary image with air clusters as solid (black) used for the velocity field simulation. c) Velocity field magnitude. d) Concentration field with continuous injection from the top.

262 the two profiles that persists over time. This agreement is then confirmed by comparing the
 263 time evolution of the second moment of the profiles in Fig. 5d. However, there is a difference
 264 at long times for low saturations. This is due to the high degree of heterogeneity within the
 265 system, that is reflected in the concentration profile. It is important to acknowledge that
 266 this heterogeneity represents the main challenge in understanding transport in unsaturated
 267 porous media. Consequently, the system might not be inherently representative, as the size
 268 of the micromodel may be insufficient to achieve a smooth enough signal. As mentioned in
 269 the introduction, one way to overcome this difficulty consists in generating a large number
 270 of different synthetic but realistic porous media with the adequate characteristics to capture
 271 the transport behavior. We propose here to investigate the use of the MPS algorithm to
 272 generate such images. Another way consists in increasing the size of the system, which is
 273 unfortunately more time consuming.

274 *2.4. Generation of unsaturated, artificial porous media: multiple-point statistics modeling* 275 *(MPS)*

276 In order to generate unsaturated, artificial porous media having the same structural
 277 and statistical properties as the experimental ones, we apply here the multi-scale MPS
 278 algorithm described in [56, 57, 58, 59] to the experimental images. MPS algorithms allow to
 279 generate images with complex shapes and structures. Their leading idea consists in retrieving
 280 information about the desired shape, spatial distribution and connection of the objects from
 281 a training image (TI), that represents a model of the expected structure. This information
 282 is then used to fill iteratively the simulation grid, resulting in a synthetic medium with a
 283 spatial distribution based on the previous characteristics. Further details on the multi-scale
 284 MPS algorithm used in this work can be found in the Supplemental Information.

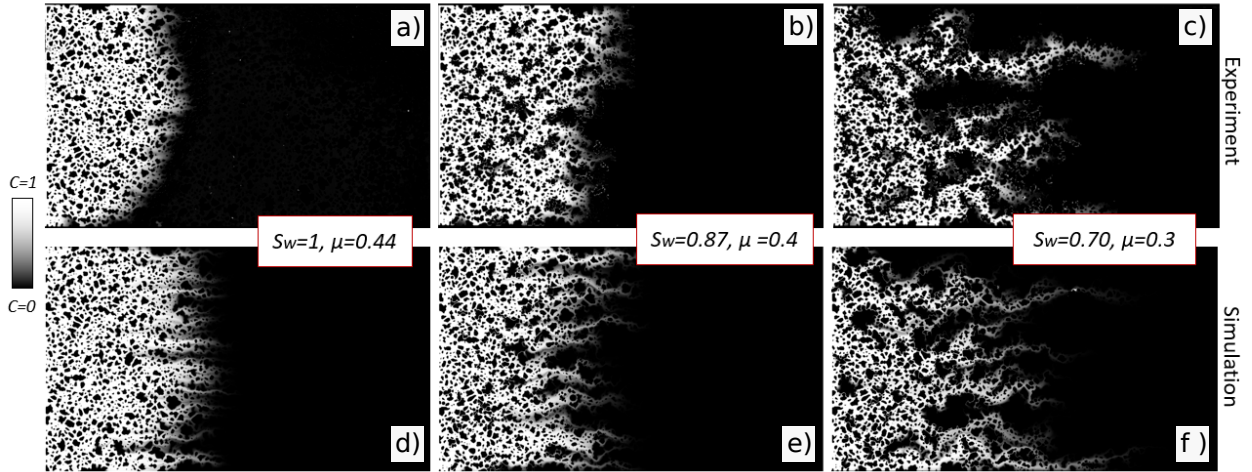


Figure 4: Comparison of experimental and simulated concentration fields at the same mean position of the front μ (first moment of the concentration profile) for three saturation values. μ is normalized by the medium length L_x . $C = 1$ corresponds to $C = C/C_{max}$

285 The MPS algorithm is applied here with training images derived from experiments and
 286 consisting of two-fluid-phase distributions (air/water) in porous media. The training images
 287 considered here are not the experimental images, but cleaned versions of these images ob-
 288 tained by removing non-physical artefacts resulting from the image processing, such as some
 289 air clusters completely enveloping grains or water contained in grains. Elements of small size
 290 whose effect on the flow is negligible are also suppressed. As detailed in the Supplementary
 291 Information, the MPS algorithm parameters are chosen as a trade-off between the simulation
 292 time and the quality of the results. The generated images present small defects that are not
 293 physical: discontinuities of the different phases, absence of water meniscus between grains
 294 and air clusters, inclusions in grains or air clusters. These defects may be lessened with other
 295 configuration parameters for the MPS algorithm, but at the cost of longer simulation times.
 296 Instead, we apply here a post-processing algorithm to the generated images to suppress these
 297 defects (see Supplemental Information).

298 2.4.1. Validation of the MPS algorithm method for flow and transport in MPS generated 299 images

300 The quality of the resulting generated images was assessed on three different saturation
 301 values ($S_w = 1, S_w = 0.87$ and $S_w = 0.70$). We conducted a comparison of various structural
 302 characteristics between the experimental and the MPS generated images. These character-
 303 istics include the distribution of pores and throats, as well as the size distribution of air
 304 clusters. The MPS algorithm proved to be effective in accurately replicating the structural
 305 properties of unsaturated porous media as discussed in the Supplemental Information. In
 306 addition, we compared flow and transport properties of the generated structures and the
 307 experimental ones. To this goal, we simulated the velocity and concentration fields using

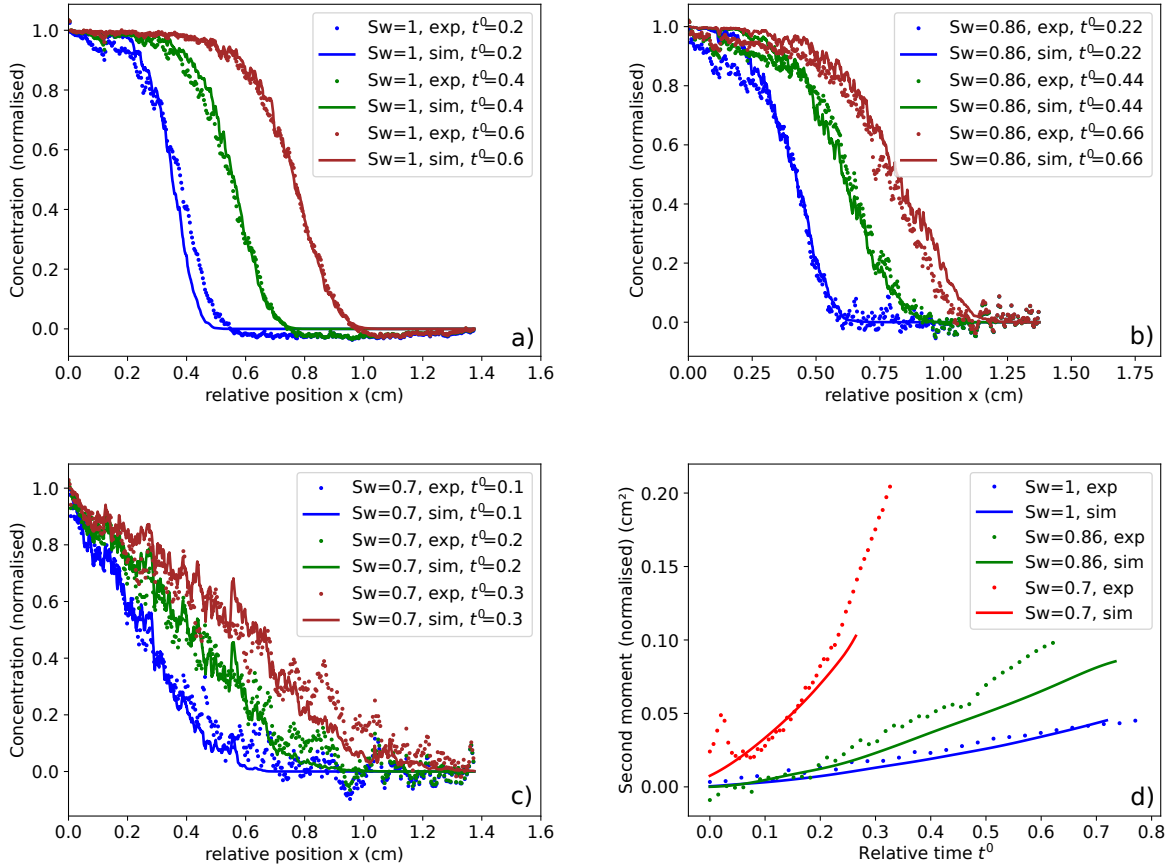


Figure 5: a-c) Comparison of experimental and simulated concentration profiles for the same air/solid configuration and three saturation values ($S_w = 1$, $S_w = 0.86$ and $S_w = 70$) at three normalized times. d) Comparison of the second moment evolution with the normalized time t' for the three saturations. An offset has been subtracted to the second moment for a better comparison of the slopes.

308 the Lattice Boltzmann method (LBM) described above. As presented in the Supplemental
 309 Information, the velocity fields show a very good agreement.

310 Furthermore, Fig. 6 shows the concentration fields in the experimental and generated
 311 images for three saturations. The patterns of dispersion, such as the preferential flow paths
 312 and the stagnant dead end zones, are correctly reproduced for the three saturations. Also,
 313 the transport properties, characterised by the concentration profiles and the second moment
 314 of the dispersion, showed a very good agreement as well (see Supplemental Information file).

315 In summary, the dispersion behaviour showed consistency between the generated and ex-
 316 perimental porous media over all investigated saturation levels. The methodology presented
 317 in this study provides a valuable means of investigating dispersion in unsaturated porous
 318 media over a wide range of saturations, including different phase configurations and porous
 319 media sizes.

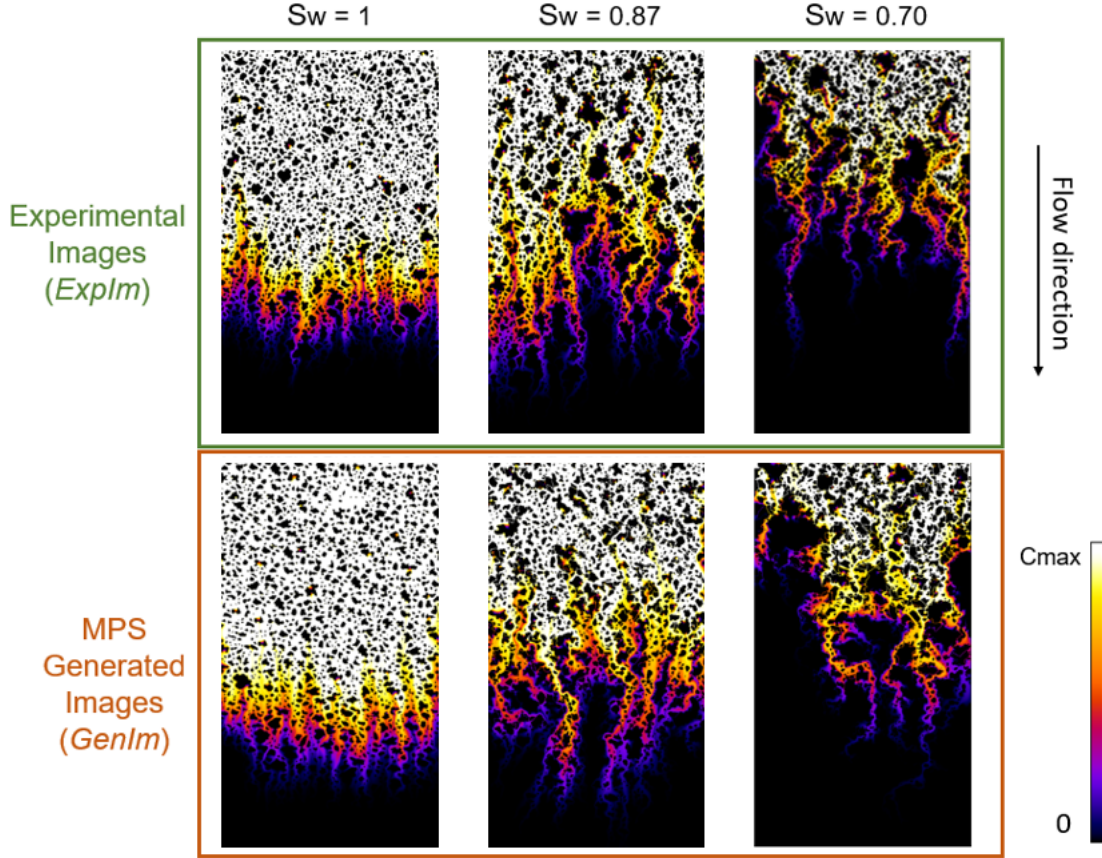


Figure 6: Assessment of the MPS method to study flow and transport. The flow and transport have been simulated using LBM with the original experimental images and the MPS generated images. Simulated concentration fields are given for three saturation values at $t = 1.2 \cdot 10^5$ LB units, $C_{\max} = 1$.

320 3. Numerical results

321 3.1. Image datasets

322 By conducting multiphase flow experiments, we obtained phase distributions from co-
 323 injection, covering a saturation range from 0.55 to 1. Our dataset resulting from experiments
 324 consists of 25 images. From this dataset, we extracted sub-images, called "training images"
 325 (TI) to generate new realizations. Using a sufficiently large number of training images, we
 326 can create a training image dataset that covers the various phase configurations present in
 327 the micromodel and takes into account their inherent variability.

328 As explained above, two different approaches are employed to deal with the heterogeneity
 329 of the unsaturated porous media. We can either analyse a large number of small generated
 330 images, or we can analyse one single, larger image. This results in two different sets of data:

- 331 • The "small size" dataset: This dataset comprises images that are approximately equiv-
 332 alent in size to the micromodel ($L_y^* = 1980$ pixels, $L_x^* = 3780$ pixels or $L_y = 0.90$

333 cm, $L_x = 1.73$ cm). To capture the system's variability, we generate multiple realiza-
 334 tions from each training image. This dataset enables us to study short-term dispersion
 335 phenomena within a computationally feasible time-frame.

- 336 • The "large size" dataset: the images within this dataset are approximately four times
 337 longer ($L_y^* = 1980$ pixels, $L_x^* = 18000$ pixels, or $L_y = 0.90$ cm and $L_x = 8.3$
 338 cm). However, due to their larger dimensions, simulating flow and transport in these
 339 images involves significantly higher computational costs (9000 processors were used in
 340 this case, compared to 180 for the shorter images). Therefore, only a limited number
 341 of these longer images was used.

342 3.2. Influence of water saturation on flow properties (small size dataset)

343 In this section, we investigate the influence of saturation on the flow properties, such
 344 as permeability, tortuosity and velocity distribution which are computed from the velocity
 345 fields (see Fig. 7).

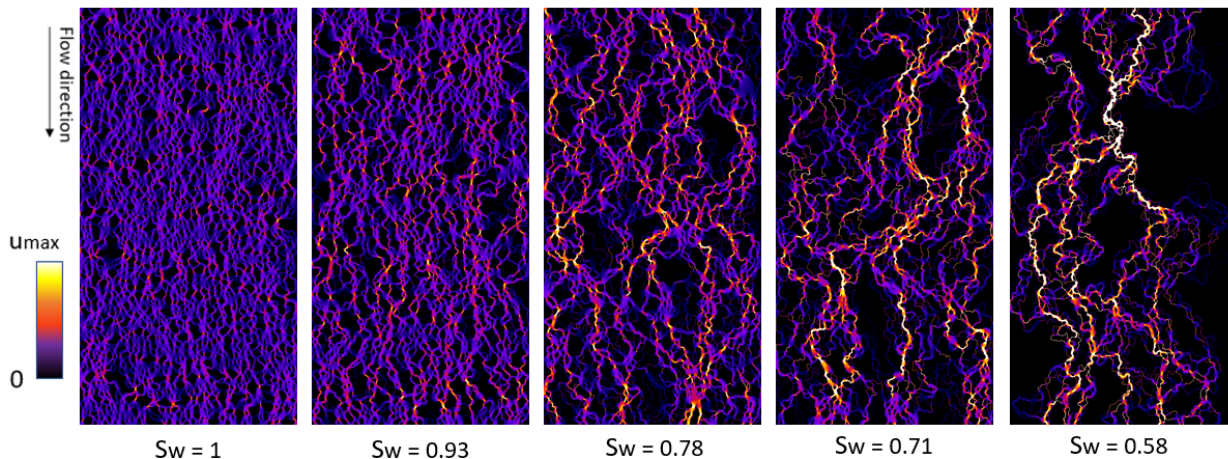


Figure 7: Norm of the velocity fields normalized by the mean flow rate for different saturations (MPS generated images). u_{max} is different for every case.

346 3.2.1. Permeability

347 Considering the fact that many permeability models incorporate the water content as a
 348 parameter, we define $\theta = \phi S_w$ to allow comparisons, where $\phi = 0.66$ is constant.

349 Fig. 8a illustrates the evolution of the effective permeability $kk_r(S_w)$, where k_r is the
 350 relative permeability corresponding to the water content θ . kk_r increases as the water
 351 content, or saturation, increases. In the fully saturated medium ($S_w = 1$, $\theta = \phi = 0.66$), the
 352 permeability equals 20 Darcy. As the saturation decreases to its minimal value ($S_w = 0.55$
 353 and $\theta = 0.40$), the relative permeability tends to zero. Please note, that in this case, the
 354 effective permeability of the fully saturated micromodel is much higher than values provided

355 in the Experimental setup. This is due to the fact, that inlet and outlet tubings included in
 356 the experimental acquisition of the permeability reduce the latter.

357 Numerous experimental and numerical studies have extensively explored the relationship
 358 between porosity, water content and permeability in saturated and unsaturated media (see
 359 for instance [60, 61]). Many of them propose a power law relationship with the porosity or
 360 the saturation (e.g. [62, 63]). Because the effective permeability tends to zero for a non zero
 361 value of water content, we fit our data using the following relation: $kk_r = R(\theta - \theta_0)^c$, with
 362 $R = 153$, $c = 2.2$, and $\theta_0 = 0.3$. And thus

$$kk_r(S_w) = R\phi^c(S_w - S_0)^c, \quad (4)$$

363 with $S_0 = \theta_0/\phi$.

364 In summary, the evolution of the effective permeability of the medium is consistent with
 365 certain classical models that establish the relationship between permeability and porosity in
 366 experimental systems. Consequently, the effective permeability kk_r of the generated images
 367 can be modelled by empirical laws with physical parameters.

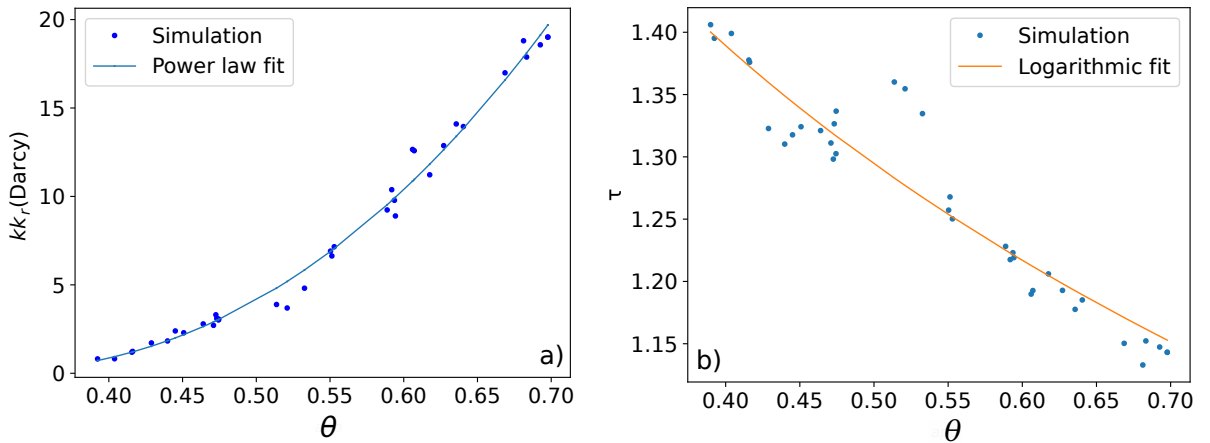


Figure 8: a) Effective permeability kk_r as a function of the water content $\theta = \phi S_w$. The continuous line corresponds to the following power law fit: $kk_r = R(\theta - \theta_0)^c$, with $(R, c, \theta_0) = (159.3, 2.3, 0.3)$. b) Tortuosity τ as a function of the water content θ . The continuous line is a logarithmic fit: $\tau = 1 - p \ln \theta$, with $p = 0.43$.

368 3.2.2. Tortuosity

369 Tortuosity quantifies the complexity of the flow paths within the porous material. A
 370 simple approach to calculate tortuosity is as follows: $\tau = \frac{\langle |\mathbf{u}| \rangle}{\langle |u_x| \rangle}$, where $|\mathbf{u}|$ is the velocity
 371 norm and $\langle |u_x| \rangle$ is the average streamwise velocity component.

372 In Fig. 8b we show that tortuosity decreases with increasing saturation, suggesting that
 373 flow paths become more tortuous at low saturations, which can be observed from the velocity
 374 fields shown in Fig. 7. At lower saturations (or water content) the tortuosity reaches a
 375 value of 1.4, indicating that the transverse and longitudinal velocities are of the same order
 376 of magnitude. Here again, there is a lack of consistency in models that incorporate the
 377 connection between tortuosity and saturation. However, numerous models exist to explain

378 the relationship between tortuosity and porosity (see [64] for more information), among them
 379 logarithmic models as for example proposed by [65]. We applied this logarithmic model to
 380 fit our data:

$$\tau = 1 - p \ln \theta, \quad (5)$$

381 with $p = 0.43$.

382 In summary, the evolution of flow tortuosity aligns with classical models that describe
 383 the relationship between tortuosity and porosity in experimental model systems. We remind
 384 that we include the gas in the definition of porosity (water content).

385 3.2.3. Flow velocity distribution

386 In Fig. 9a, the distribution of normalized velocity, $|\mathbf{u}|/\langle|\mathbf{u}|\rangle$, is plotted for various satura-
 387 tion values. It is observed that as the saturation decreases, the velocity distribution becomes
 388 wider, and the tail of the distribution extends towards lower velocities. This widening sug-
 389 gests the formation and expansion of dead-end regions within the medium. Notably, at lower
 390 saturation levels, a second peak emerges at very low velocities ($|\mathbf{u}|/\langle|\mathbf{u}|\rangle \sim 10^{-5}$), indicating
 391 the presence of nearly stagnant zones in the flow. Additionally, there is a spreading towards
 392 high velocities with increasing saturation, especially below $S_w = 0.70$. These high velocities
 393 arise from the formation of preferential paths with high velocity. This flow heterogeneity
 394 can be quantified using the velocity standard deviation σ_u . Fig. 9b reveals that the stan-
 395 dard deviation decreases as the saturation increases. For the lowest saturation values, the
 396 standard deviation is approximately three times higher than that in saturated conditions.
 397 The velocity standard deviation can be reasonably fitted with a power law:

$$\sigma_u \simeq aS_w^c + b \quad (6)$$

398 with $(a, b, c) = (0.62, 0.02, -1.8)$.

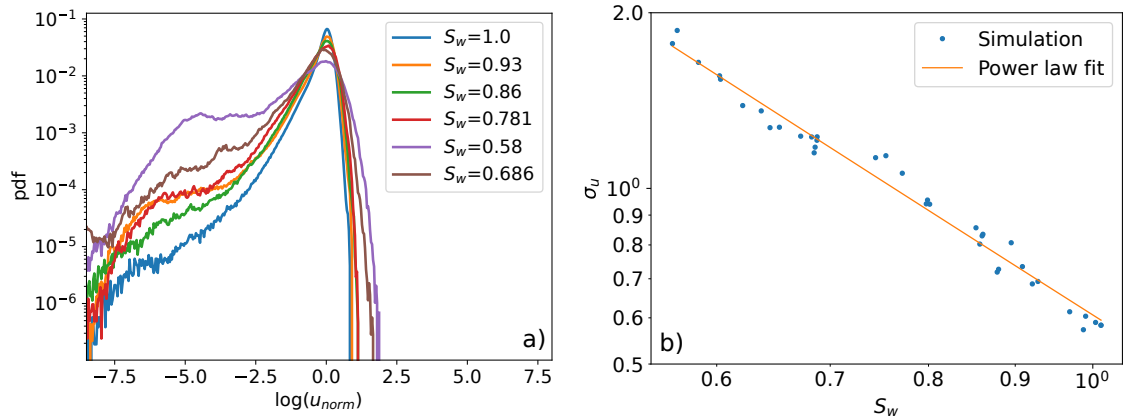


Figure 9: a) For different saturations, distributions of $\log(u_{norm})$, with $u_{norm} = |\mathbf{u}|/\langle|\mathbf{u}|\rangle$, the interstitial velocity magnitude normalized by the mean interstitial velocity. b) Normalized standard deviation of the interstitial velocity as a function of saturation. The line corresponds to a power law fit: $\sigma_u = aS_w^c + b$, with $(a, b, c) = (0.62, 0.02, -1.8)$.

399 *3.3. Effect of water saturation and Peclet number on transport (small size dataset)*

400 We perform LBM simulations on MPS generated images, covering the experimental range
 401 of saturation $[0.55, 1]$ and explore the following range of Peclet numbers: $Pe \in [0.001, 1000]$,
 402 where the Peclet number is defined as

$$Pe = \frac{\langle |\mathbf{u}| \rangle d_{\text{pore}}}{D_m}. \quad (7)$$

403 $\langle |\mathbf{u}| \rangle$ is the mean local velocity, d_{pore} the mean pore diameter of the porous medium and D_m
 404 the molecular diffusion coefficient.

405 *3.3.1. Effect of saturation on dispersion*

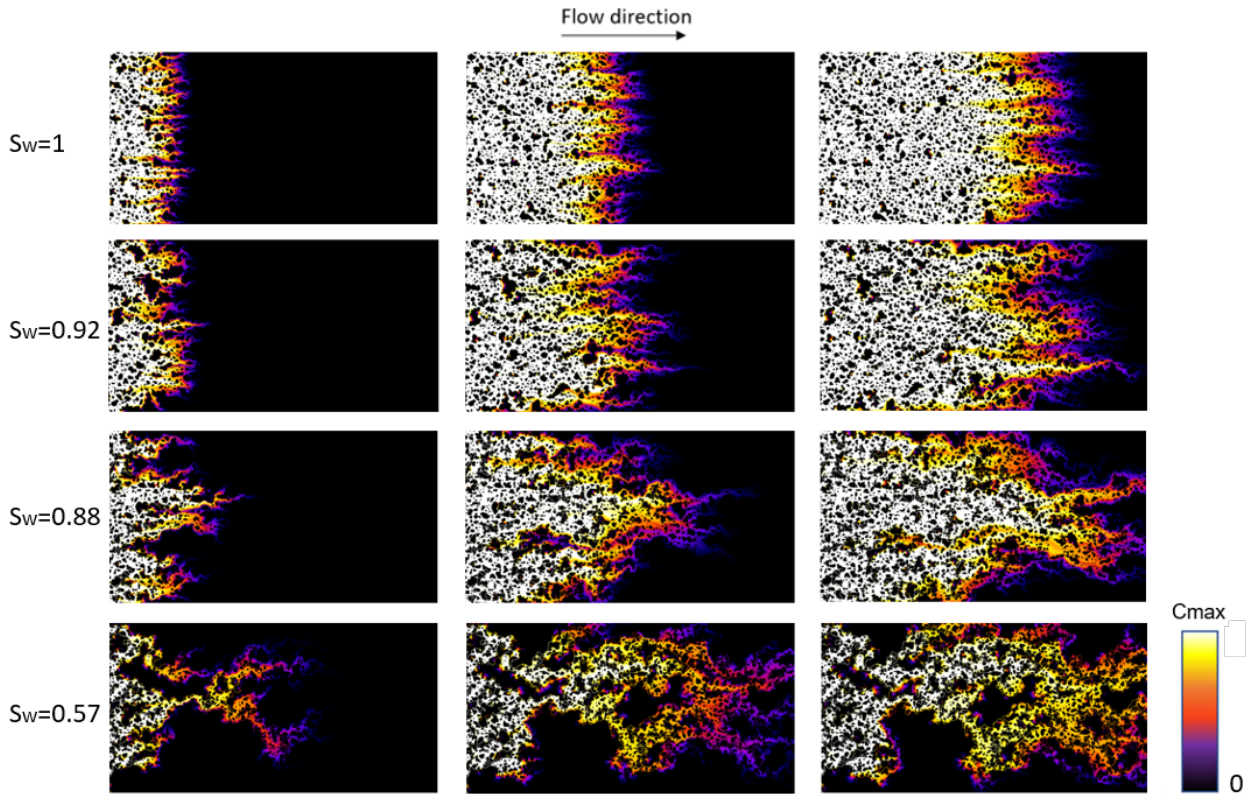


Figure 10: Concentration fields for four saturation values and three mean positions of the concentration front ($\mu_0 = 0.18L_x$, $\mu_1 = 0.43L_x$, $\mu_2 = 0.65L_x$) with $Pe = 100$.

406 Fig. 10 shows the time evolution of the concentration fields for different saturations and
 407 $Pe = 100$. At full saturation the concentration front is relatively flat. As the saturation
 408 decreases, the front becomes more heterogeneous and spreads faster with time. In particular,
 409 preferential flow paths and dead end zones become more pronounced. We characterise
 410 dispersion by the second moment as a function of time, as shown in Fig. 11a. For this
 411 Peclet number, we observe that the second moment is not proportional to time, in saturated
 412 and unsaturated conditions. The dispersion is therefore non-Fickian for any saturation. To

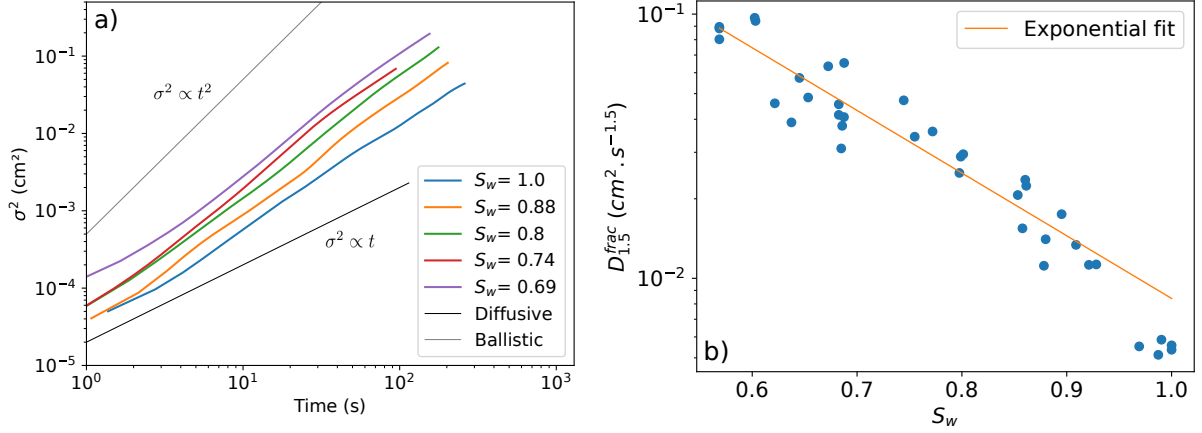


Figure 11: a) Second moment as a function of time for different saturations with $Pe = 100$. b) Fractional dispersion coefficient as a function of saturation. The continuous line represents an exponential trend, $D_{1.5}^{frac} = b \exp^{-S_w a}$, with $(a, b) = (5.5, 2.0)$, diffusive regime: $\sigma^2 \propto t$, ballistic regime: $\sigma^2 \propto t^2$.

413 quantify the dispersion magnitude, we compute the mean of the power law coefficient α
 414 for all the realizations and saturations, which is equal to $\langle \alpha \rangle = 1.5$. We then compute the
 415 fractional dispersion coefficient with this exponent using Eq. (1). Results are presented
 416 in Fig. 11b. The fractional dispersion coefficient increases by more than a decade as the
 417 saturation decreases from $S_w = 1$ to $S_w = 0.55$. Roughly speaking, the decay follows an
 418 exponential trend for the unsaturated cases, with a small inflection around $S_w = 1$. This
 419 trend is consistent with the observation in 3D porous media by [11, 66], although these
 420 authors fit their data with a function different from ours (power law decay).

421 3.3.2. Effect of the Peclet number on dispersion

422 In this section, we explore the influence of the Peclet number on dispersion, starting with
 423 saturated conditions followed by unsaturated conditions.

424 *Saturated medium.* Fig. 12 illustrates how the power law index α evolves with the Peclet
 425 number. At high Peclet numbers, α exceeds one (~ 1.4) and decreases as the value of the
 426 Peclet number decreases. The exponent reaches 1 for Peclet numbers less than one. In
 427 other words, for high Peclet numbers, the dispersion is dominated by advection, leading
 428 to non-Fickian behaviour. The non-Fickian character slowly diminishes with decreasing
 429 Peclet number as diffusion becomes more effective. When diffusion and advection are of
 430 the same order ($Pe \in [1, 10]$), α reaches 1 (Fickian transport). We also compute the pure
 431 diffusion case ($Pe = 0$) and observe, as expected, that the transport is Fickian ($\alpha = 1$) and
 432 the value of the dispersion is below the molecular diffusion coefficient, allowing to define a
 433 diffusive tortuosity $\tau_d = \frac{1}{D^*(Pe=0)} = 2.15$. The effect of Peclet number on dispersion has been
 434 thoroughly studied in the literature for saturated porous media [67, 68, 69]. Most of these
 435 studies report the evolution of the dispersion coefficient, *i.e.* assuming Fickian transport
 436 $\alpha = 1$, as a function of the Peclet number. For comparison, we thus compute in Fig. 12 a
 437 normalized effective dispersion coefficient, imposing $\alpha_{imposed} = 1$: $D^* = D_{\alpha=1}^{frac} / D_m$. For high

438 Peclet number values, D^* is approximately proportional to the Peclet number. As the Peclet
 439 number decreases, D^* slowly converges to a constant value smaller than 1. This evolution
 440 with the Peclet number is thus in good agreement with the literature.

441 In conclusion, we have shown that while the evolution of the dispersion coefficient with
 442 the Peclet number is qualitatively consistent with the literature, the transport deviates from
 443 the Fickian one for $Pe \gtrsim 10$. In this range, the value of α rises above 1.

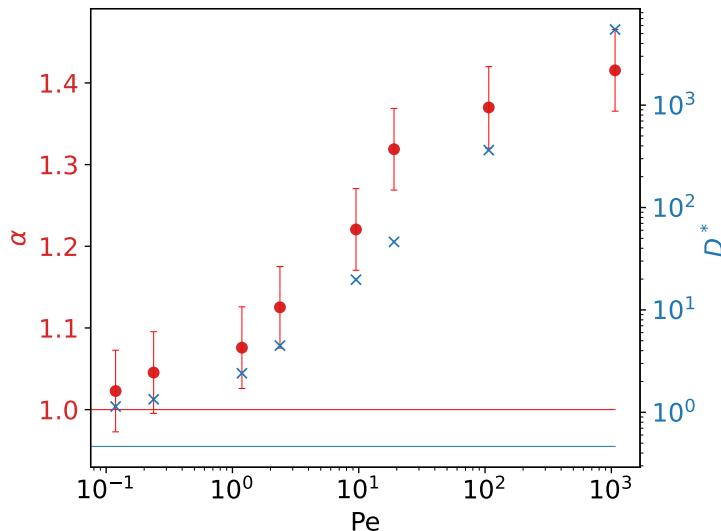


Figure 12: Evolution of the power law index α (dots) and the normalized effective dispersion coefficient $D^* = D_{\alpha=1}^{frac}/D_m$ (crosses) with the Peclet number for the saturated case $S_w = 1$. The values for no flow condition ($Pe = 0$) are shown with a red and blue line for $\alpha(Pe = 0)$ and $D^*(Pe = 0)$ respectively. Error bars of α are estimated from the power law fit.

444 *Unsaturated medium.* We now examine the influence of the Peclet number on α and $D^* =$
 445 $D_{\alpha=1}^{frac}/D_m$ for different saturations. Fig. 13a displays how the exponent α changes as the
 446 Peclet number varies. For all saturations we observe a similar dependence on the Peclet
 447 number as in the saturated case. Namely, there is a transition from Fickian behaviour
 448 ($\alpha = 1$) at low Pe to non-Fickian behaviour ($\alpha \sim 1.4$) at higher Peclet number. However,
 449 we note that the Peclet number of the transition depends on the saturation, with the tran-
 450 sition occurring at lower Pe (almost two decades) for the lowest saturation. Also, for lower
 451 saturations, the transition is stiffer. Fig. 13b shows the evolution of the normalised effec-
 452 tive dispersion coefficient D^* ($\alpha = 1$) with the Peclet number. Similarly to the saturated
 453 case, the dispersion coefficient increases with the Peclet number. As for the saturated case
 454 the dispersion coefficient is constant for low Peclet number. At a given Peclet number, D^*
 455 starts to increase with the onset of the transition depending on the saturation. For lower
 456 saturation, the onset occurs at a significantly lower value of the Peclet number. For a given
 457 Peclet number, D^* is therefore higher at lower saturation. Interestingly, the onset of the
 458 transition for α and D^* is of the same order of magnitude of Peclet number. Note that the

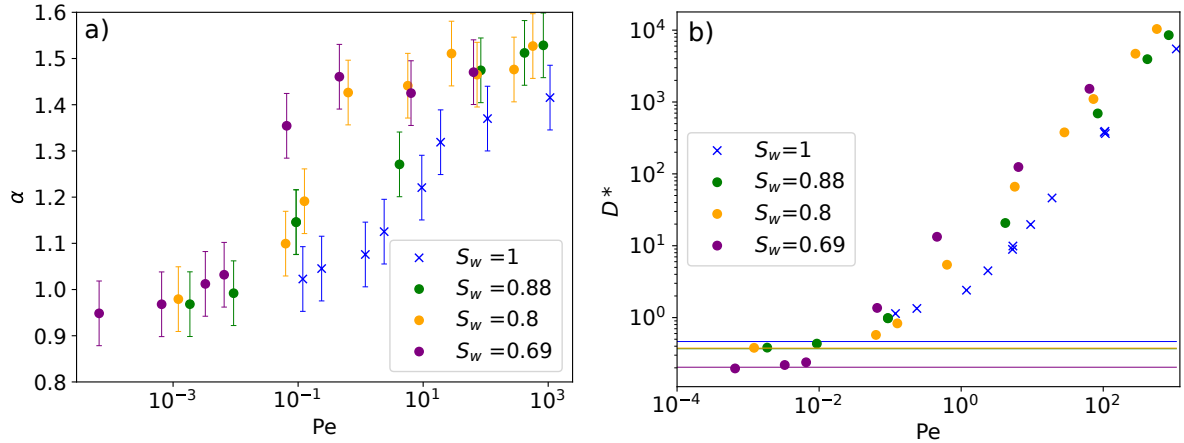


Figure 13: Evolution of the power law index α a) and normalized dispersion coefficient b) with the Peclet number for different saturation values. The values of D^* for no flow condition are shown by horizontal lines. Error bars of α are estimated from the power law fit.

459 value of D^* in purely diffusive conditions ($Pe = 0$, straight line in Fig. 13) decreases with
 460 reducing saturation: the diffusive tortuosity of the medium thus rises with saturation.

461 Fig. 14 shows the evolution of α with saturation for different, specific Peclet numbers.
 462 For high Peclet numbers, α is relatively independent of saturation, but as the Peclet number
 463 decreases, the dependency becomes more pronounced. In 2D regular structures, Velasquez
 464 et al. [17] observed a transition from Fickian to non-Fickian behavior with decreasing
 465 water saturation. 3D transport experiments using NMR imaging in homogeneous rock with
 466 various degrees of saturation [70] show non-Fickian dispersion even in saturated conditions,
 467 with a non-Fickian character enhanced by lower saturations. Our results are therefore
 468 representative of a general tendency and most likely not constraint by the geometry of the
 469 porous media. As discussed in the introduction, similar micromodel transport experiments
 470 have been performed by [3, 33, 4, 71] using cylindrical pillars of different diameters. Although
 471 they observed non-Fickian transport for the unsaturated case, the exponent α is difficult
 472 to compare quantitatively. For example, ballistic behaviour ($\alpha = 2$) was observed in [33],
 473 whereas in our case α is below 1.5 even at high Peclet number. This difference could
 474 be attributed to the porous structure of the micromodel, which strongly influences the
 475 immiscible distribution.

476 To conclude, dispersion is non-Fickian for a larger range of Peclet numbers in unsaturated
 477 conditions. At high Peclet number, transport is dominated by advection even in saturated
 478 conditions and transport is non-Fickian. For intermediate Peclet number, dispersion is
 479 Fickian only for high saturations but not for smaller saturations. For sufficiently low Peclet
 480 numbers, dispersion is dominated by diffusion and becomes Fickian even for the lowest
 481 saturations.

482 3.4. Large size dataset simulations

483 In the previous section, we observed a non-Fickian behavior for a large range of param-
 484 eters. However, it is worth recalling that asymptotic non-Fickian behavior is only expected

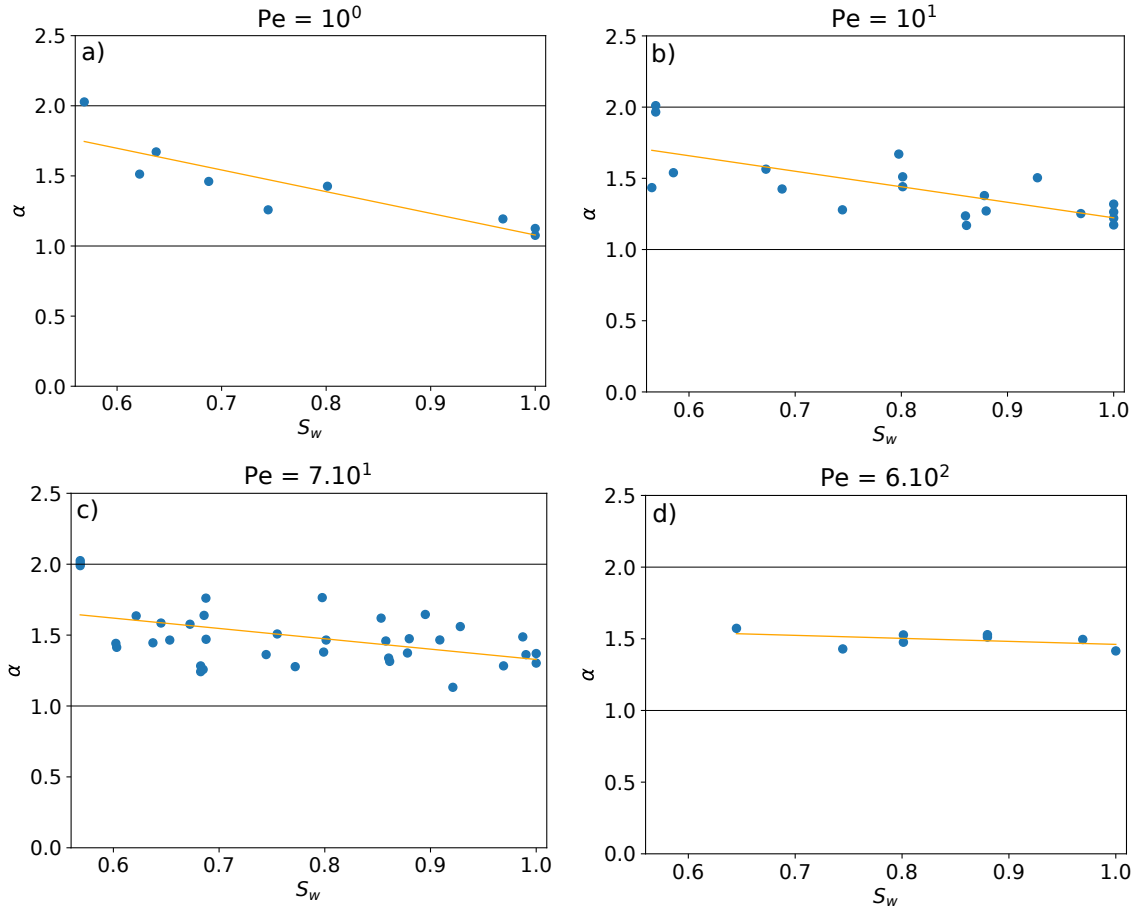


Figure 14: Dependence of the power law index α with saturation for different Peclet numbers. The trend is highlighted by a linear fit to each curve. The blue points correspond to values computed for the short dataset $L_x = 3780$. a) $Pe = 10^0$, $\alpha_{fit} = -0.05S_w + 1.5$ b) $Pe = 10^1$, $\alpha_{fit} = -0.05S_w + 1.5$ c) $Pe = 7 \times 10^1$, $\alpha_{fit} = -1.08S_w + 2.4$ d) $Pe = 6 \times 10^2$, $\alpha_{fit} = -1.7S_w + 2.8$.

485 for non-finite variance of the velocity distribution. As shown in Fig. 9, the variance of the
486 velocity field increases with decreasing saturation while remaining finite. This means that
487 one should expect the dispersion to be Fickian in an asymptotic regime, suggesting that the
488 observed non-Fickian regime would only be transient. For this reason, we performed several
489 simulations with a very large domain as described above. Fig. 15a shows the variance as
490 function of time for five different saturations with an intermediate Peclet number, $Pe = 5$.
491 The evolution of the variance confirms the non-Fickian tendency over longer times, but no
492 change in the temporal behavior (e.g. transition to the asymptotic regime) was observed
493 for any saturation. We conclude that our domain is still too short to reach an asymptotic
494 regime. However, since the exponents α in the large size domain (Fig. 15b) and the smaller
495 one are similar (α increases with decreasing saturation), it indicates that the small size sam-
496 ples are large enough and more efficient for quantifying the transport properties in partially
497 saturated porous media.

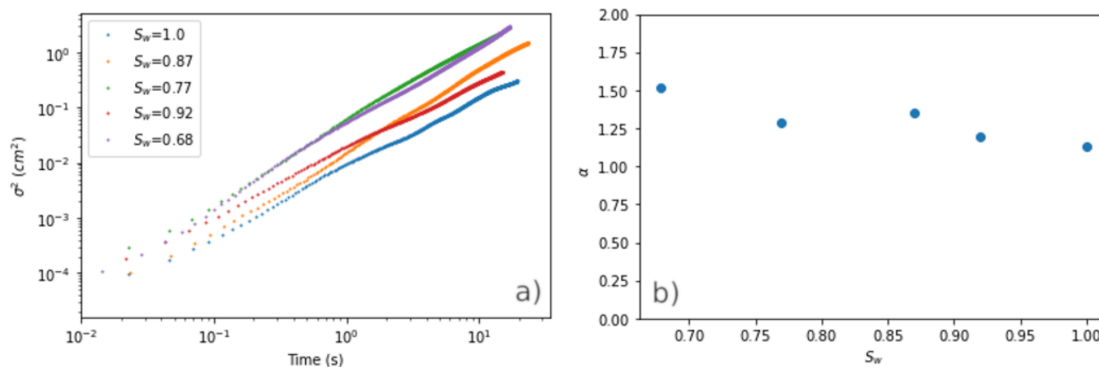


Figure 15: Results for large system size (18000×1980 pixels²) for $Pe = 5$. a) Displacement variance as function of time for different saturations. b) Corresponding power law index α as a function of saturation.

498 4. Conclusions and Discussion

499 In this article we investigated passive transport phenomena in two-dimensional unsatu-
500 rated porous media coupling experiments and numerical simulations. Two-phase distribu-
501 tions (air/water) for different saturations were obtained by means of co-injection experiments
502 in a micromodel reproducing the topology of a Bentheimer sandstone. From these experi-
503 mental images, we generated new images using a multi-scale MPS algorithm. Using Lattice
504 Boltzmann method, we computed velocity and concentration fields in both experimental and
505 generated images, for saturated and unsaturated conditions. We showed that the velocity
506 distributions were very similar. The concentration profiles were in very good agreement
507 and the variance indicates that the dispersion characteristics of the experimental images are
508 well reproduced by the MPS images. Consequently, MPS allowed the generation of a large
509 number of unsaturated porous media images having a new topology but similar properties.

510 For a large number of samples covering the saturation range between 0.55 and 1, we
511 computed transport for different Peclet numbers. The main result of this study is the

512 observation of non-Fickian behaviour for a wide range of these parameters. This behaviour
513 is characterised by a variance that increases with time according to a power law with an
514 exponent α . We have determined the evolution of this exponent as a function of saturation
515 and Peclet number. Overall, α increases with decreasing saturation due to the increase in
516 flow heterogeneity, and increases with the Peclet number. This behavior has been confirmed
517 by large size simulations. However, these large size domain simulations did not exhibit the
518 expected transition to a Fickian regime.

519 As discussed in the introduction, the physical origin of anomalous transport lies in the
520 strong heterogeneity of velocity field and residence time (see also [71]). It is therefore not
521 surprising to find that decreasing the water saturation enhances anomalous behavior, as
522 it increases both the extent of the velocity distribution, but also the number of stagnant
523 zones. What is more interesting, however, is the fact, that while saturation greatly increases
524 the prefactor of the power law D_* , it changes only slightly the exponent α (around 1.5
525 at high Peclet number). The exponent seems to depend mainly on the Peclet number:
526 1 for low values and 1.5 for high values. In fact, diffusion increases the exchange rate
527 between different velocity zones. Reducing the Peclet number therefore decreases the effects
528 of extreme velocity values and thus favours normal transport. However, we observe that
529 decreasing saturation shifts the Peclet number value of the transition by increasing the
530 extent of the high and low velocity zones. We also note, that, while the α exponent in our
531 case becomes relatively constant for high Peclet number, other studies in different geometries
532 show higher exponents [33, 16, 17]. This suggests that the exponent value may depend on
533 the geometry of the porous structure.

534 There are several ways to extend this study. First of all, it would be worthwhile to repeat
535 this method for 3D geometry. If 3D X-ray tomography allows the determination of air and
536 water distribution in natural media, the main drawback is the small sample size. A 3D
537 MPS algorithm could therefore be used to generate many other configurations to perform
538 statistical analysis on more realistic rock. This would also allow lower saturation values to
539 be investigated. Another possible direction could be to analyse more carefully the origin of
540 the non-Fickian regime. For example, one could use the CTRW framework to determine the
541 resident time distribution. One possible outcome of such approach would be the estimation
542 of the duration of this transient non-Fickian regime.

543 **Acknowledgment**

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545 authors would like to thank Sarah Bouquet and Guillaume Batôt for using the MPS and LB
546 code respectively.

547 **Supplemental Information**

548 Supplementary material related to this article can be found in the Supplemental Informa-
549 tion file. The SI file provides further details on the image processing and the MPS algorithm.
550 It also precises the LBM schemes to solve Darcy-Brinkman and Advection-diffusion equa-
551 tions. Additional results are also illustrated.

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